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<thead>
<tr>
<th>Project</th>
<th><strong>IEEE 802.16 Broadband Wireless Access Working Group</strong> [<a href="http://ieee802.org/16">http://ieee802.org/16</a>]</th>
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<tbody>
<tr>
<td>Title</td>
<td><strong>Systematic CID Allocation and Relay Path Configuration</strong></td>
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<tr>
<td>Date</td>
<td><strong>2007-3-5</strong></td>
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<thead>
<tr>
<th>Source(s)</th>
<th>Aik Chindapol</th>
<th>Jimmy Chui</th>
<th>Hui Zeng</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Siemens Corporate Research</td>
<td>Princeton, NJ, 08540, USA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Teck Hu</td>
<td>Siemens Networks</td>
<td>Boca Raton, FL 33431, USA</td>
</tr>
<tr>
<td></td>
<td>Yuan-Ying Hsu</td>
<td>Telcordia Applied Research Center</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Taiwan Co.</td>
<td>Taipei, Taiwan</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Jen-Shun Yang, Tzu-Ming Lin, Wern-Ho Sheen, Fang-Ching Ren, Chie Ming Chou, I-Kang Fu</td>
<td>Industrial Technology Research Institute (ITRI)/National Chiao Tung University (NCTU), Taiwan 195,Sec. 4, Chung Hsing Rd. Chutung, Hsinchu, Taiwan 310, R.O.C.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Byung-Jae Kwak, Sungcheol Chang, Young-il Kim</td>
<td>ETRI</td>
<td>161, Gajeong-Dong, Yuseong-Gu, Daejeon, Korea 305-350</td>
</tr>
<tr>
<td></td>
<td>Changkyoon Kim, Kyu Ha Lee, Hyung Kee Kim</td>
<td>Samsung Thales Co., Ltd</td>
<td>San 12-1, Nongseo-Dong, Giheung-Gu, Yongin-City, Gyeonggi-Do, Korea 446-712</td>
</tr>
<tr>
<td></td>
<td>Kenji Saito, Takashi Inoue</td>
<td>KDDI R&amp;D Laboratories Inc.</td>
<td>Hikarino-oka 7-1, Yokosuka, Kanagawa 239-0847, Japan</td>
</tr>
<tr>
<td></td>
<td>Sungjin Lee</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Voice: +1 609 734 3364  
Fax:  +1 609 734 6565  
Email: aik.chindapol@siemens.com

Voice: +886-2-37895177#4558  
Fax:  +886-2-26552078  
Email: yyhsu@tarc-tw.research.telcordia.com

Voice: +886-3-5914616  
Fax:  +886-3-5820263  
Email: jsyang@itri.org.tw

Voice: +82-42-860-6618  
Fax:  +82-42-861-1966  
Email: bjkwak@etri.re.kr

Voice: +82-31-280-9919  
Fax:  +82-31-280-1620  
Email: changkyoon.kim@samsung.com

Voice: +81 46 847 6347  
Fax:  +81 46 847 0947  
Email: saito@kddilabs.jp
Re: IEEE 80216j-07_007r2:“Call for Technical Comments and Contributions regarding IEEE Project 802.16j”

Abstract
This document describes the route update procedures with efficient CID management.

Purpose
This contribution is provided as input for the IEEE 802.16j baseline document.

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Systematic CID Allocation and Relay Path Configuration

21 Introduction

In 802.16e, each connection (both management and data) is identified by a Connection ID (CID) [2]. There is no routing required; data is transmitted solely between the BS and the MS. In a centralized multi-hop relay system, all relay stations form a tree topology with MR-BS as the root. The routing for each MS is decided by the MR-BS. The routing path could be mainly based on the network topology and other number of factors such as measured channel qualities, QoS of each connection, fairness, etc.

This contribution proposes to use CID assignment in a multi-hop relay system as a means to indicate network topology and further help the MR-BS to perform routing path selection. In this scheme, each relay station is assigned a range of CIDs for which the relay is responsible for decoding and forwarding. The parent node will control a superset of this CID range, and any child nodes (both RS and MS) will be assigned disjoint subsets of the CID range. Because of the structure of this CID assignment, the MR-BS could compute the relay path simply based on CIDs of destination station and each relay station can recognize its packets and forward them to corresponding stations. In this way, the routing can be maintained automatically along with CID assignment and thus significantly decrease complexity, signal overhead, and path setup latency. The systematic CID allocation could also help to reduce the delay when handoff of MRS or MS occurs, which could be achieved by locating new anchor station to maintain the topology quickly.

The proposal for this implementation has the following advantages:

- Simplified operation of the relay
- Reduction of overhead and delay in route updates
- Reuse of existing signaling to reflect topology changes due to the movement of MRSs or MSs
- Quickly locating the anchor RS for fast handoff while MRSs or MSs move

2.2 General Description

A unidirectional connection between BS and MS or between BS and RS is established for service flow traffic, and each connection is identified by a connection identifier (CID) [2][3]. The CID for each connection is inserted within the MAC header of a packet. When it is received, first each station checks whether the CID of the packet is for itself or for its subordinate stations. Each station accepts the packet and does the process if the packet is intended to itself or its subordinate station. Otherwise, it ignores the packet and does nothing.

Each station can distinguish the received packets by examining the CID in the MAC header or in the MAP-IE, and this can be used to maintain the routing structure. By combining CIDs with the routing for each connection, the routing structure can be updated and maintained easily along with CIDs, and the overall overheads for the routing can be reduced.

3.3 Partitioning of Integers

3.3.1 General Idea

To systematically assign CIDs to the MR-BS and RSs, the proposed CID allocation mechanism adopts the partitioning of the positive integers into subsets. In this section, we describe two methods of the partitioning of integers. This can be accomplished by factorization into bit partition, or contiguous blocks. The idea is to map these subsets to nodes in a network (assumed to be a tree topology) which will assist in identifying the placement of the node in the tree.
Each node of the tree represents a subset of $\mathbb{Z}$, the set of all positive integers. The leaves of the tree are pairwise disjoint subsets of the integers. Each parent node is a superset of the union of its children. For example, in Figure 1, $B \ D \ E$ and $D \ H \ J \ K$. The tree can grow; at a particular node, its children must satisfy two conditions. 1) the children must be subsets of the parent node; 2) the children are pairwise disjoint.

Due to this structure, any node (root, leaf, or intermediary) can determine whether a particular integer will exist in its subtree (with itself as the root). Intermediary nodes must distinguish between two types of integers; those that terminate at the node (terminal integers), and those that do not terminate at the node (non-terminal integers). We provide two examples of integer partitioning that assume only one terminal integer at each intermediary node, and briefly mention how multiple terminal integers (per intermediary node) can be attained.

**3.2 Examples of integer partitioning: contiguous integer blocks**

This is a simple implementation. The root node represents $\mathbb{Z}$. Each of its children (1st tier nodes) are assigned a contiguous range of $\mathbb{Z}$ (and pairwise disjoint). For a particular 1st tier node (with range $[p_1, p_2]$), its children (2nd tier nodes) are each assigned a contiguous subset of $[p_1, p_2]$ (and pairwise disjoint). This process continues for the entire tree. In Figure 2a, we demonstrate how the tree in Figure 1 can partition the integers using contiguous integer block methods.

In Figure 2a, the terminal integers for nodes B, C, D can be set to 1000, 2000, and 400 respectively. Allowing multiple terminal integers per intermediary node is trivial.

**3.3 Examples of integer partitioning: bit partition**

Each decimal number could also be converted into a binary number. Assume there are at most $2^k$ RSs could associate with one RS or BS directly, $k$ bits would be used to identify each RS in the same level. The 1st tier
nodes that associate to the MR-BS directly would have CIDs with all possible number in lowest $k$ bits. Their 2
children (2nd tier nodes) is identified by left shifting $k$ bits of parent CID and set lowest $k$ bits. This process
continues for the entire tree. In this manner, the CID (without leading 0s) of any RS will be the prefix of CIDs
4of all its subordinate RSs.

5 To convert these values into subsets of $\mathbb{Z}$ (as discussed in Section 3.1) is simple; a $n$th tier node will have a
unique $nk$-bit sequence to identify itself, then the range this node could assign will be all numbers with this $nk$-
7bit sequence in the middle and begin with arbitrary number of “0”s as its prefix and with arbitrary combination
8of 0 and 1 as its suffix. The condition as set out in Section 3.1 is satisfied. We also demonstrate how the tree in
9Figure 1 can partition the integers using bit partition method in Figure 2b.

4 CID Assignment

We describe the CID allocation for both contiguous integer partitioning method and bit partition method in
19the following. This structured CID assignment can be used to assign tunnel CIDs (i.e. CIDs terminating at an
20 access RS), or RS and MS management CIDs. Our examples describe the assignment of tunnel CIDs.

14.1 CID allocation using contiguous integer partitioning method

We perform this CID assignment scheme ignoring the MS in the topology. This method is compatible with the
23 notion of encapsulating CIDs [9] or tunnel CIDs.
3In Figure 3, the MR-BS indicates the range of CIDs that each RS is responsible for, as well as the CID for the connection for each RS node. For each subordinate RS, the assigned CID range has to be a subset of its connecting RS.

4.2 CID allocation using bit partition method

We first define a parameter $2^k$ to identify the maximum number of subordinate RSs that the MR-BS or a RS could have. If $k=0$, each RS could only have one subordinate RS. For $1^n$-tier RSs, which connect to the MR-BS directly, the MR-BS assigns IDs sequentially from 1 to $2^k$ as shown in Figure 4 by setting different values of the 11 lowest $k$ bits of the ID. We only show the lowest 8 bits of CIDs in Figure 4. For other $n$-tier RSs, the MR-BS left shifts $k$ bits of its parent ID and sets the lowest $k$ bits according to the arriving sequence of the RS. For example, RS $T$ and RS $U$ comes one after another to associate with RS $O$ (ID: 00 01 00 11) after RS $R$ and RS $S$ in Figure 3. To assign an ID to RS $T$, the MR-BS first perform left shift 2 bits of its parent ID and gets 01 00 11 00, and then it sets the lowest 2 bits as 10 since it is the third RS that attaches to RS $O$. Similarly, the MR-BS assigns 1601 00 11 11 to RS $U$ after RS $T$.

Figure 4: CID assignment for 4.2.

225 Relay Path Configuration

The proposed systematic CID allocation has significantly advantage of simple relay path configuration, and it is possible to be used for transmission using tunnels and transmission using station CID. In the following, we show examples to describe transmission using tunnels as well as using station’s CID. Both contiguous and bit partitioning methods could be applied two solutions of relay path configuration.

285.1 Examples of relay path configuration using tunneling solution

We take figure 5 for example. There are two MSs, which associate to RS $L$ (CID: 00 01 01 00) and RS $G$. 
The whole relay path could be divided into two segments: from the source RS to the MR-BS and from the MR-BS to the destination RS. For upstream frames, each RS could easily know its parent CID by right shifting $k$ bits of its own CID. For example, the CID of access RS $L$ is 00 01 01 00, so its parent CID is 00 00 01 01 by right shifting 2 bits of its CID. For downstream frame received from its parent RS, the RS needs to determine if it should accept, forward, or discard the frame. When the tunneling [8] [10] is applied for relaying, the Tunnel CID could be set as the CID of destination RS. Each intermediate RS could compute if the destination RS belongs to its subordinate RSs by the algorithm in Figure 6. First of all, the RS compares if the destination CID is equal to its own CID and accepts the frame if these two CIDs are the same. If the match fails, it perform $k$-bit right shift of the destination CID and do the comparison with its own CID. If the shifted destination CID is the same as its own CID, it forwards the frame to its subordinate RS. Otherwise, it continues do the right shift and comparison for (maximal level-current level) times and discards the frame if all matches are failed. For example, RS C would know that RS G is its subordinate RS by right shifting the destination CID once.

![Figure 5: An example of relay path configuration using bit partition method.](image)

![Figure 6: Subordinate RS differentiation algorithm](image)
Figure 7: An example of relay path configuration using contiguous integer partitioning method. The number in parenthesis is the range of CIDs that the MR-BS could allocate to the subordinate RS.

Similarly with contiguous integer partitioning shown in Figure 7, the MR-BS keeps records of the access RS for each MS. For data directed towards MS2, the MR-BS sends the data to the access RS with CID 60. Since this CID belongs to the range of CID of the RS C, it forwards the data to the RS G. Meanwhile, the RS B ignores this data as the CID is not within its range. The similar procedure can be done on the uplink.

5.2 Relay path configuration using non-tunneling solution

For non-tunneling configuration (MDHO or cooperative relaying), encapsulation of CIDs [6] can be used to perform path configuration.

6 Proposed Text

6.3.1.3.1 Addressing Scheme for Relaying

In the procedure of network entry and initialization for a new RS, the MR-BS may systematically assign a range of basic CIDs MT-CIDs, and T-CIDs for a RS. There are two CID range assignment method: contiguous integer blocks as in Figure 6.3.1.3.X (a) and bit partition as in Figure 6.3.1.3.X (b). In the bit partition assignment, the MR-BS sets the lowest $k$ bits in ascending order to RSs for RSs associated to the MR-BS directly where the maximum number of RSs the MR-BS or a RS could serve is $2^k$. For other level-n RSs, which need $n$ hops to reach the MR-BS, the MR-BS left shifts $k$ bits of its parent CID and sets the lowest $k$ bits according to the arriving sequence of the RS.
Figure 6.3.1.3.Y: CID range allocation example, (a) contiguous integer block, (b) bit partition method.

6.3.2.3.6 Ranging response (RNG-RSP) message

Insert the following text at the end of the 6.3.2.3.6:

The following TLV parameter shall be included in the RNG-RSP message when transmitted during RS initial entry to the network. The MR-BS could assign the range of RSs.

CID allocation method
Range of CID for RS

[Insert the following subclause into section 6.3.2.3]

6.3.2.3.XX RS CID Allocation Indication (CID_ALLOC-IND) message

The CID_ALLOC-IND message shall be transmitted by the MR-BS to the RS when the network topology is changed or the range of CIDs needs to be modified at any time. Upon receiving CID_ALLOC-IND, the RS shall update its range of CIDs accordingly. The message format is shown in Table XX.

Table XX CID_ALLOC-IND message format

<table>
<thead>
<tr>
<th>Syntax</th>
<th>Size</th>
<th>Note</th>
</tr>
</thead>
<tbody>
<tr>
<td>CID_ALLOC-IND _Message_Format() {}</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Management Message Type (TBD)</td>
<td>8 bits</td>
<td></td>
</tr>
<tr>
<td>CID_Alloc_method</td>
<td>3 bits</td>
<td>0: contiguous method</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1: bit partition method</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2-7: reserved</td>
</tr>
<tr>
<td>If (CID_Alloc_method = =0) {}</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Start number of CID</td>
<td>16 bits</td>
<td>Starting point of the CID</td>
</tr>
<tr>
<td>End number of CID</td>
<td>16 bits</td>
<td>End point of the CID number</td>
</tr>
</tbody>
</table>
If (CID_Alloc_method == 1) {
    New CID for the RS 16 bits
    Hop count 8 bits The new hop count of the RS to the MR-BS
    K_Code 8 bits The new maximum number of subordinate RSs that a RS could have
}

Basic CID (in the MAC header)
The CID in the MAC header is the Basic CID for this RS

11.6 RNG-RSP management message encodings
Insert the following entries into Table 367:

<table>
<thead>
<tr>
<th>Name</th>
<th>Type (1 byte)</th>
<th>Length</th>
<th>Value (variable-length)</th>
<th>PHY Scope</th>
</tr>
</thead>
<tbody>
<tr>
<td>CID allocation method</td>
<td>xx</td>
<td>1</td>
<td>Used to indicate the CID allocation method of RSs 0: contiguous integer block method 1: bit partition method</td>
<td>OFDMA</td>
</tr>
<tr>
<td>Range of management CID for RS</td>
<td>xx</td>
<td>4</td>
<td>If CID range allocation method==0: Byte#0-1: start number of CID Byte#2-3: end number of CID If CID range allocation method==1: Byte#0: hop count Byte#1: the maximum number of subordinate RSs that a RS could have Byte#2-3: reserved</td>
<td>OFDMA</td>
</tr>
</tbody>
</table>

6.3.25 Relay path management and routing
Each relay station is assigned a range of CIDs for which the relay is responsible for decoding and forwarding. The CID range is assigned by the MR-BS, and are transmitted to RSs via RNG-RSP management messages. During operation, the RS is only responsible for listening to CIDs transmitted within this range.

The BS is responsible for managing the entire CID range. Each RS connected to a parent node (BS or RS) is assigned a subset of the CIDs assigned to the parent node. These subsets are non-overlapping.

By assigning a systematic CID to each RS, the MR-BS already specifies the relay routing path of the connection.

7 References
[1] IEEE C802.16j-06/004r1, “Recommendations on IEEE 802.16j”.


IEEE C802.16j-06/014r1, “Harmonized definitions and terminology for 802.16j Mobile Multihop Relay”

IEEE C802.16j-06/015, “Harmonized Contribution on 802.16j (Mobile Multihop Relay) Usage Models”

IEEE C802.16j-07-126, “Routing with CID Encapsulation”

IEEE C802.16j-06/274, “Proposal on addresses, identifiers and types of connections for 802.16j”.

IEEE C802.16j-06/254, “Fast Connection Establishment and Maintenance with Relays”.

IEEE C802.16j-06/170, “Connection Identification and Transmission for Relay Support”