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Re:	IEEE 80216j-07_007r2:" Call for Technical Comments and Contributions regarding IEEE Project 802.16j"			
Abstract	This document describes the route update procedures with efficient CID management.			
Purpose	This contribution is provided as input for the IEEE 802.16j baseline document.			
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1

# Systematic CID Allocation and Relay Path Configuration

### 21 Introduction

3 In 802.16e, each connection (both management and data) is identified by a Connection ID (CID) [2]. There 4 is no routing required; data is transmitted solely between the BS and the MS. In a centralized multi-hop relay 5 system, all relay stations form a tree topology with MR-BS as the root. The routing for each MS is decided by 6 the MR-BS. The routing path could be mainly based on the network topology and other number of factors such 7 as measured channel qualities, QoS of each connection, fairness, etc.

8 This contribution proposes to use CID assignment in a multi-hop relay system as a means to indicate 9network topology and further help the MR-BS to perform routing path selection. In this scheme, each relay 10station is assigned a range of CIDs for which the relay is responsible for decoding and forwarding. The parent 11node will control a superset of this CID range, and any child nodes (both RS and MS) will be assigned disjoint 12subsets of the CID range. Because of the structure of this CID assignment, the MR-BS could compute the relay 13path simply based on CIDs of destination station and each relay station can recognize its packets and forward 14them to corresponding stations. In this way, the routing can be maintained automatically along with CID 15assignment and thus significantly decrease complexity, signal overhead, and path setup latency. The systematic 16CID allocation could also help to reduce the delay when handoff of MRS or MS occurs, which could be 17achieved by locating new anchor station to maintain the topology quickly.

18 The proposal for this implementation has the following advantages:

- 19 Simplified operation of the relay
- 20 Reduction of overhead and delay in route updates
- 21 Reuse of existing signaling to reflect topology changes due to the movement of MRSs or MSs
- 22 Quickly locating the anchor RS for fast handoff while MRSs or MSs move
- 23

## 242 General Description

A unidirectional connection between BS and MS or between BS and RS is established for service flow 26traffic, and each connection is identified by a connection identifier (CID) [2][3]. The CID for each connection 27 is inserted within the MAC header of a packet. When it is received, first each station checks whether the CID of 28 the packet is for itself or for its subordinate stations. Each station accepts the packet and does the process if the 29 packet is intended to itself or its subordinate station. Otherwise, it ignores the packet and does nothing.

30 Each station can distinguish the received packets by examining the CID in the MAC header or in the MAP-31IE, and this can be used to maintain the routing structure. By combining CIDs with the routing for each 32connection, the routing structure can be updated and maintained easily along with CIDs, and the overall 33overheads for the routing can be reduced.

## 343 Partitioning of Integers

### 353.1 General Idea

36 To systematically assign CIDs to the MR-BS and RSs, the proposed CID allocation mechanism adopts the 37partitioning of the positive integers into subsets. In this section, we describe two methods of the partitioning of 38integers. This can be accomplished by factorization into bit partition, or contiguous blocks. The idea is to map 39these subsets to nodes in a network (assumed to be a tree topology) which will assist in identifying the 40placement of the node in the tree.

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1 Each node of the tree represents a subset of  $\mathbb{Z}$ , the set of all positive integers. The leaves of the tree are 2pairwise disjoint subsets of the integers. Each parent node is a superset of the union of its children. For 3example, in Figure 1, B D E and D H J K. The tree can grow; at a particular node, its 4children must satisfy two conditions. 1) the children must be subsets of the parent node; 2) the children are 5pairwise disjoint.

6 Due to this structure, any node (root, leaf, or intermediary) can determine whether a particular integer will 7exist in its subtree (with itself as the root). Intermediary nodes must distinguish between two types of integers; 8those that terminate at the node (terminal integers), and those that do not terminate at the node (non-terminal 9integers). We provide two examples of integer partitioning that assume only one terminal integer at each 10intermediary node, and briefly mention how multiple terminal integers (per intermediary node) can be attained.

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С

G

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13 14

Figure 1: an example of a network tree (an abstract model)

Е

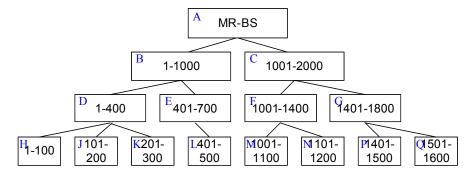
В

D

### 153.2 Examples of integer partitioning: contiguous integer blocks

16 This is a simple implementation. The root node represents **Z**. Each of its children (1<sup>st</sup> tier nodes) are 17assigned a contiguous range of **Z** (and pairwise disjoint). For a particular 1<sup>st</sup> tier node (with range  $[p_1, p_2]$ ), its 18children (2<sup>nd</sup> tier nodes) are each assigned a contiguous subset of  $[p_1, p_2]$  (and pairwise disjoint). This process 19continues for the entire tree. In Figure 2a, we demonstrate how the tree in Figure 1 can partition the integers 20using contiguous integer block methods.

21 In Figure 2a, the terminal integers for nodes B, C, D can be set to 1000, 2000, and 400 respectively. 22Allowing multiple terminal integers per intermediary node is trivial.



24Figure 2a: partitioning of integers using contiguous blocks. The choice of range length being multiples of 100 is arbitrary.

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23

#### 273.3 Examples of integer partitioning: bit partition

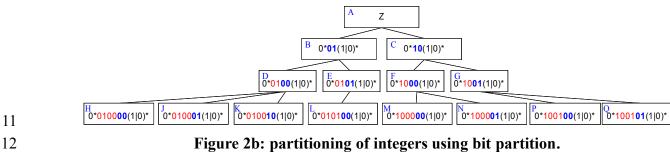
Each decimal number could also be converted into a binary number. Assume there are at most  $2^k$  RSs could 29associate with one RS or BS directly, *k* bits would be used to identify each RS in the same level. The 1<sup>st</sup> tier

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1 nodes that associate to the MR-BS directly would have CIDs with all possible number in lowest k bits. Their 2children ( $2^{nd}$  tier nodes) is identified by left shifting k bits of parent CID and set lowest k bits. This process 3continues for the entire tree. In this manner, the CID (without leading 0s) of any RS will be the prefix of CIDs 4of all its subordinate RSs.

To convert these values into subsets of Z (as discussed in Section 3.1) is simple; a n<sup>th</sup> tier node will have a 5 6unique *nk*-bit sequence to identify itself, then the range this node could assign will be all numbers with this nk-7bit sequence in the middle and begin with arbitrary number of "0"s as its prefix and with arbitrary combination 8 of 0 and 1 as its suffix. The condition as set out in Section 3.1 is satisfied. We also demonstrate how the tree in 9Figure 1 can partition the integers using bit partition method in Figure 2b.

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13

14 Note that a simple way of allowing multiple terminal values at intermediary nodes is to merge nodes. For 15example, the logical nodes H and J can represent the same physical node.

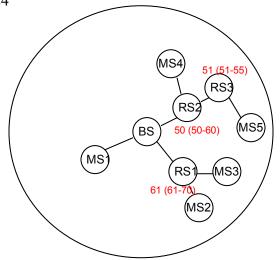
16

#### **CID Assignment** 174

18 We describe the CID allocation for both contiguous integer partitioning method and bit partition method in 19the following. This structured CID assignment can be used to assign tunnel CIDs (i.e. CIDs terminating at an 20access RS), or RS and MS management CIDs. Our examples describe the assignment of tunnel CIDs.

214.1 CID allocation using contiguous integer partitioning method

22We perform this CID assignment scheme *ignoring the MS in the topology*. This method is compatible with the  $2^{3}_{24}$ notion of encapsulating CIDs [9] or tunnel CIDs.



1Figure 3: CID Assignment for 4.1

2

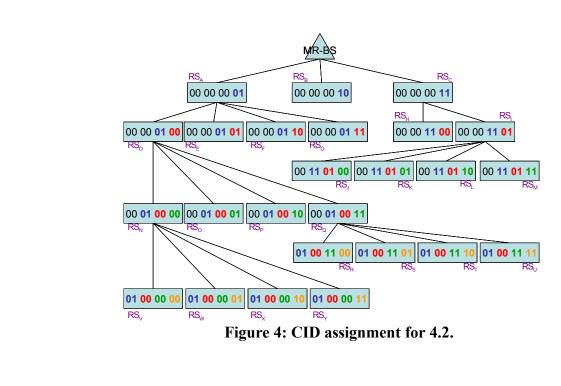
3In Figure 3, the MR-BS indicates the range of CIDs that each RS is responsible for, as well as the CID for the 4connection for each RS node. For each subordinate RS, the assigned CID range has to be a subset of its 5connecting RS.

6

#### 74.2 CID allocation using bit partition method

8 We first define a parameter  $2^k$  to identify the maximum number of subordinate RSs that the MR-BS or a RS 9could have. If k=0, each RS could only have one subordinate RS. For 1<sup>st</sup>-tier RSs, which connect to the MR-BS 10directly, the MR-BS assigns IDs sequentially from 1 to  $2^k$  as shown in Figure 4 by setting different values of the 11lowest *k* bits of the ID. We only show the lowest 8 bits of CIDs in Figure 4. For other n-tier RSs, the MR-BS 12left shifts *k* bits of its parent ID and sets the lowest *k* bits according to the arriving sequence of the RS. For 13example, RS<sub>T</sub> and RS<sub>U</sub> comes one after another to associate with RS<sub>Q</sub> (ID: 00 01 00 11) after RS<sub>R</sub> and RS<sub>S</sub> in 14Figure 3. To assign an ID to RS<sub>T</sub>, the MR-BS first perform left shift 2 bits of its parent ID and gets 01 00 11 00, 15and then it sets the lowest 2 bits as 10 since it is the third RS that attaches to RS<sub>Q</sub>. Similarly, the MR-BS assigns 1601 00 11 11 to RS<sub>U</sub> after RS<sub>T</sub>.

17



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18 19

### 21

## 225 Relay Path Configuration

The proposed systematic CID allocation has significantly advantage of simple relay path configuration, and 24it is possible to be used for transmission using tunnels and transmission using station CID. In the following, we 25show examples to describe transmission using tunnels as well as using station's CID. *Both contiguous and bit* 26partitioning methods could be applied two solutions of relay path configuration.

27

### 285.1 Examples of relay path configuration using tunneling solution

29 We take figure 5 for example. There are two MSs, which associate to RS L (CID: 00 01 01 00) and RS G

12

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1(CID: 00 00 10 01), in the network. The MR-BS has records for these two MSs and knows their serving RSs. 2The whole relay path could be divided into two segments: from the source RS to the MR-BS and from the MR-3BS to the destination RS. For upstream frames, each RS could easily know its parent CID by right shifting k 4bits of its own CID. For example, the CID of access RS L is 00 01 01 00, so its parent CID is 00 00 01 01 by 5right shifting 2 bits of its CID. For downstream frame received from its parent RS, the RS needs to determine if 6it should accept, forward, or discard the frame. When the tunneling [8] [10] is applied for relaying, the Tunnel 7CID could be set as the CID of destination RS. Each intermediate RS could compute if the destination RS 8belongs to its subordinate RSs by the algorithm in Figure 6. First of all, the RS compares if the destination CID 9is equal to its own CID and accepts the frame if these two CIDs are the same. If the match fails, it perform k-bit 10right shift of the destination CID and do the comparison with its own CID. If the shifted destination CID is the 11same as its own CID, it forwards the frame to its subordinate RS. Otherwise, it continues do the right shift and 12comparison for (maximal level-current level) times and discards the frame if all matches are failed. For 13example, RS C would know that RS G is its subordinate RS by right shifting the destination CID once.

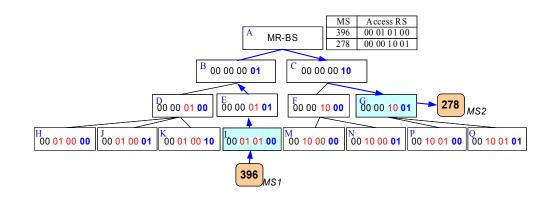


Figure 5: An example of relay path configuration using bit partition method.

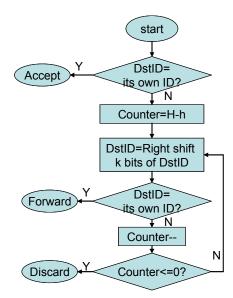
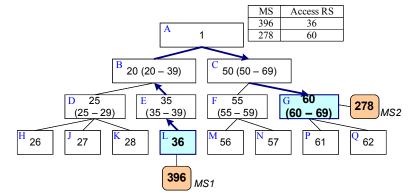




Figure 6: Subordinate RS differentiation algorithm



1

2 Figure 7: An example of relay path configuration using contiguous integer partitioning method. The

3 number in parenthesis is the range of CIDs that the MR-BS could allocate to the subordinate RS.

4

5 Similarly with contiguous integer partitioning shown in Figure 7, the MR-BS keeps records of the access 6RS for each MS. For data directed towards MS2, the MR-BS sends the data to the access RS with CID 60. 7Since this CID belongs to the range of CID of the RS C, it forwards the data to the RS G. Meanwhile, the RS B 8ignores this data as the CID is not within its range. The similar procedure can be done on the uplink.

9

### 105.2 Relay path configuration using non-tunneling solution

11 For non-tunneling configuration (MDHO or cooperative relaying), encapsulation of CIDs [6] can be used to 12perform path configuration.

13

### 146 Proposed Text

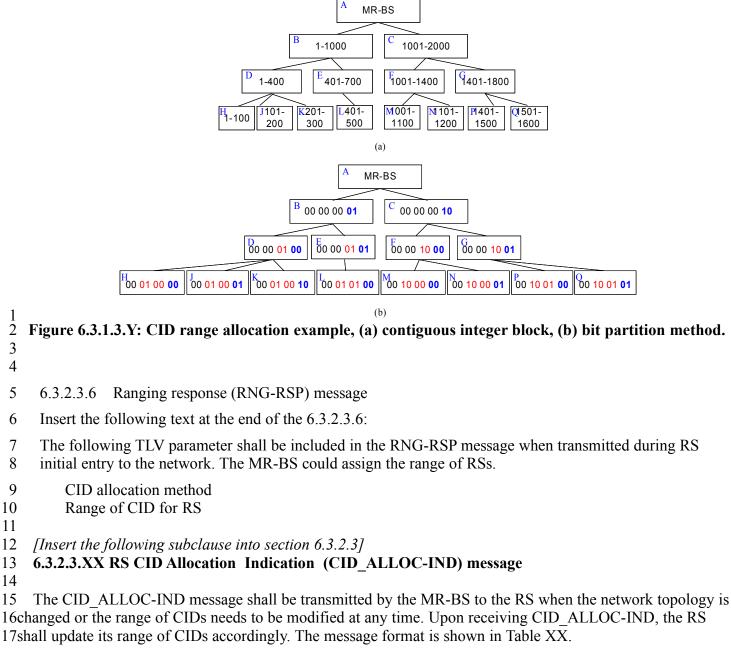
15-----Beginning of Text Changes------

16 [Add the following text into section 6.3.1.3]

### 17 6.3.1.3.1 Addressing Scheme for Relaying

In the procedure of network entry and initialization for a new RS, the MR-BS may systematically assign a range of basic CIDs MT-CIDs, and T-CIDs for a RS. There are two CID range assignment method: contiguous integer blocks as in Figure 6.3.1.3.X (a) and bit partition as in Figure 6.3.1.3.X (b). In the bit partition assignment, the MR-BS sets the lowest k bits in ascending order to RSs for RSs associated to the MR-BS directly where the maximum number of RSs the MR-BS or a RS could serve is  $2^k$ . For other level-n RSs, which need n hops to reach the MR-BS, the MR-BS left shifts k bits of its parent CID and sets the lowest k bits according to the arriving sequence of the RS.

25



18 19

Table XX CID\_ALLOC-IND message format

Syntax	Size	Note
CID ALLOC-IND Message Format() {		
Management Message Type (TBD)	8 bits	
CID_Alloc_method	3 bits	0 : contiguous method 1 : bit partition method 2-7 : reserved
If (CID_Alloc_method = =0) {		
Start number of CID	16 bits	Starting point of the CID number
End number of CID	16 bits	End point of the CID number
}		

If (CID_Alloc_method = =1) {		
New CID for the RS	16 bits	
Hop count	8 bits	The new hop count of the RS to the MR-BS
K_Code	8 bits	The new maximum number of subordinate RSs that a RS could have
}		
}		

20 21 22

- Basic CID (in the MAC header)
- The CID in the MAC header is the Basic CID for this RS
- 23 24
- 25 11.6 RNG-RSP management message encodings
- 26 Insert the following entries into Table 367:
- 27 28

Table	367 -	RNG-	RSP	message	encodings
ruore	201	10,0	ICOI	message	encounings

Name	Туре	Length	Value	PHY
	(1 byte)		(variable-length)	Scope
CID allocation method	xx	1	Used to indicate the CID allocation method of RSs 0: contiguous integer block method 1: bit partition method	OFDMA
Range of management CID for RS		4	If CID range allocation method==0: Byte#0-1: start number of CID Byte#2-3: end number of CID If CID range allocation method==1: Byte#0: hop count Byte#1: the maximum number of subordinate RSs that a RS could have Byte#2-3: reserved	OFDMA

29

30 6.3.25 Relay path management and routing

31 Each relay station is assigned a range of CIDs for which the relay is responsible for decoding and 32 forwarding. The CID range is assigned by the MR-BS, and are transmitted to RSs via RNG-RSP management 33 messages. During operation, the RS is only responsible for listening to CIDs transmitted within this range.

The BS is responsible for managing the entire CID range. Each RS connected to a parent node (BS or RS) 35 assigned a subset of the CIDs assigned to the parent node. These subsets are non-overlapping.

36 By assigning a systematic CID to each RS, the MR-BS already specifies the relay routing path of the 37connection.

38

### 39 7 References

40[1] IEEE C802.16j-06/004r1, "Recommendations on IEEE 802.16j".

1[2] IEEE 802.16-2004, "Part 16: Air Interface for Fixed and Mobile Broadband Wireless Access Systems".

2[3] IEEE 802.16e-2005, "Part 16: Air Interface for Fixed and Mobile Broadband Wireless Access Systems, 3Amendment 2: Physical and Medium Access Control Layers for Combined Fixed and Mobile Operation in 4Licensed Bands *and* Corrigendum 1".

5[4] IEEE C802.16j-06/014r1, "Harmonized definitions and terminology for 802.16j Mobile Multihop 6Relay"

- 7[5] IEEE C802.16j-06/015, "Harmonized Contribution on 802.16j (Mobile Multihop Relay) Usage Models"
- 8[6] IEEE C802.16j-07-126, "Routing with CID Encapsulation"
- 9[8] IEEE C802.16j-06/274, "Proposal on addresses, identifiers and types of connections for 802.16j".
- 10[9] IEEE C802.16j-06/254, "Fast Connection Establishment and Maintenance with Relays".
- 11[10] IEEE C802.16j-06/170, "Connection Identification and Transmission for Relay Support"