Considering all Noise Sources over a single data and power pair IEEE802.3bp Task Force

Channel Definition ad-hoc

May 2013 .

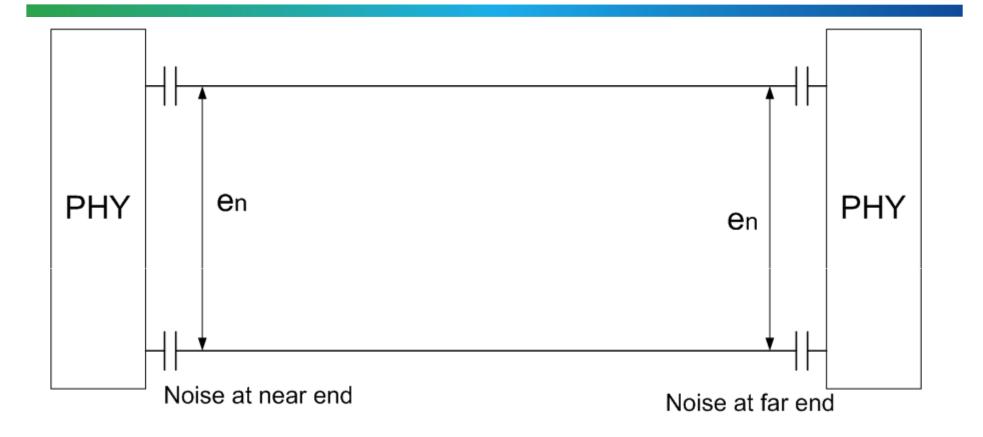
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Objectives

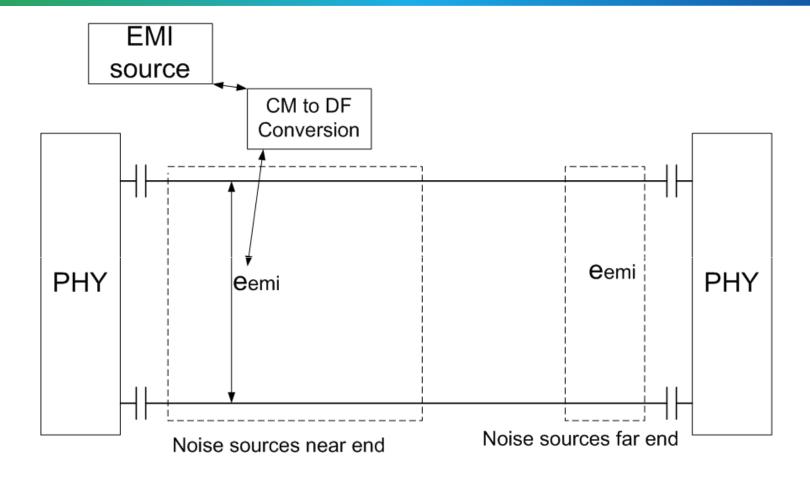
 To ensure that we cover all potential noise sources over the data pair for specifying the total differential maximum noise over the data pair.

en(f) = Maximum Noise Vs Frequency Requirement



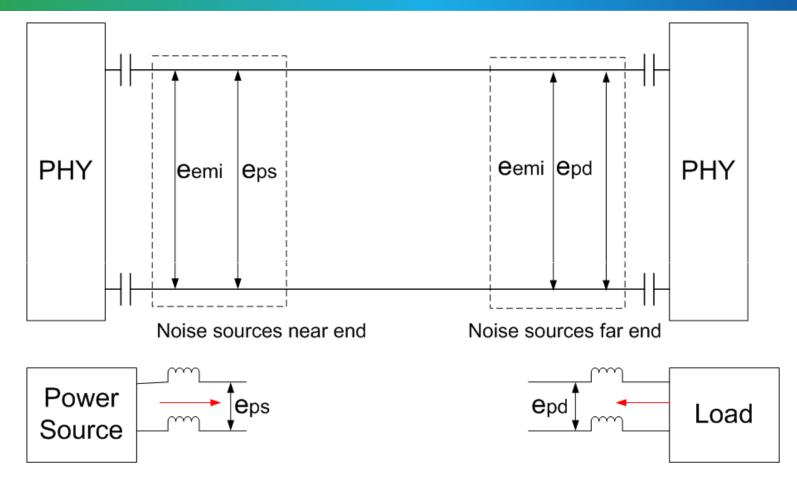
 We need to know the maximum rms noise. On as function of freuency in which data specification is met.

EMI noise source



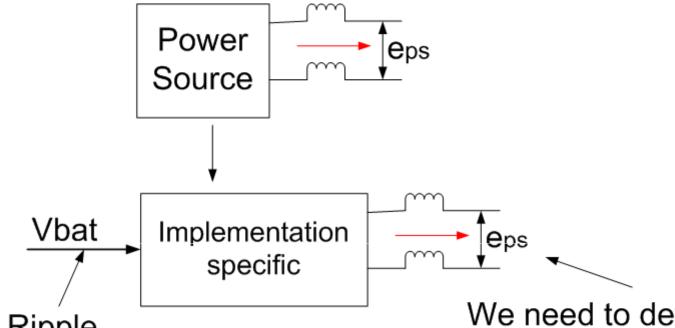
EMI is one of the noise sources that generate DM noise

Power source and load noise sources



 If power is delivered over the same data pair, we have additional noise sources at near end (power supply noise) and far end (load noise e.g. DC/DC converter noise)

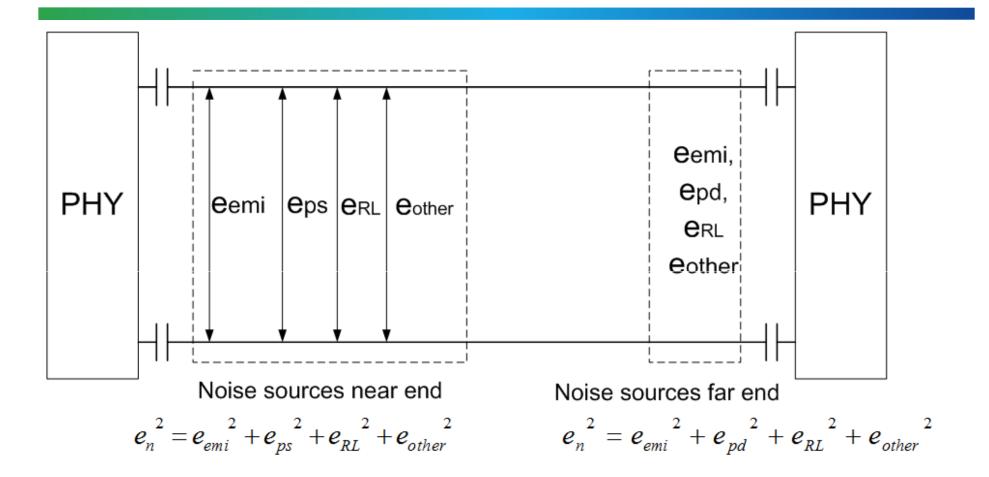
More about Power Source Noise



- Ripple
- Noise
- Transients per automotive standards (ISO7637 etc.)

We need to define eps for any frequency at Vbat and the data range operating frequencies.

Proposed general case for noise sources



- CRL is the noise gnerated by the return loss during transmision.
- Cother is other noise sources that we may add to the list including design margin

Working assumption

- Cemi on both ends is the same quantity
- Cother is unknow noise source or a design margin
- Open and Open are independent noise sources
- CRL on both sides is the same quantity
- As a result:
- Total Worst Case Noise on each end is(*): $e_n^2 \ge e_{emi}^2 + e_{ps}^2 + e_{pd}^2 + e_{RL}^2 + 2 \cdot e_{other}^2$
- Assuming all sources have the same weight: $e_n^2 \ge 6 \cdot e^2$
- The upper limit spec. for each noise source as function of frequency:

$$e_{rms}(f) \le \frac{e_n(f)}{\sqrt{6}} = 0.4 \cdot e_n(f)$$

- Which is ~7.8dB below en.
- (*) If there are more noise sources the model above can be extended accordingly)

More about the evaluation of spec limits

- There are other ways to plug in the design margin. Probably different ways will generate a bit different results.
- Without design margin, due to 4 known noise sources, the total noise with the same working assumptions shown previously will be:

$$e_n^2 \ge e_{emi}^2 + e_{ps}^2 + e_{pd}^2 + e_{RL}^2 = 4 \cdot e^2$$

The upper limit spec. for each noise source as function of frequency:

$$e_{rms}(f) \le \frac{e_n(f)}{\sqrt{4}} = 0.5 \cdot e_n(f)$$

- Which is ~6dB below en. (not including design margin)
- The negeral case for the upper limit of a noise source of a list of S noise sources:

$$e_{rms}(f) \le \frac{e_n(f)}{\sqrt{S}}$$

Summary

- There are additional noise sources that are needed to be taken when noise limits are defined for **C**emi(f) or any other noise source.
- When total en(f) is known, any noise source ei need to meet:
 ei(f) < en(f) by at least -10*log(S)[dB] for any noise source i from a list of i=1 to S noise sources.

Proposed next steps

- To get en test data that ensures meeting data requirements over the specified channel.
- To generate a list of all known noise sources
- To derive the spec values for each noise source.
- It is highly practical from power source and load point of view, to define a detailed table of differential noise per frequency over the frequency range of interest.
- It is important to define the noise also for low frequencies outside the transmiting range e.g. from 1-2Hz to 1-10MHz. It will allow more flexibility and cost effective power source when power over data will be implemented.

Discussion

Thank You