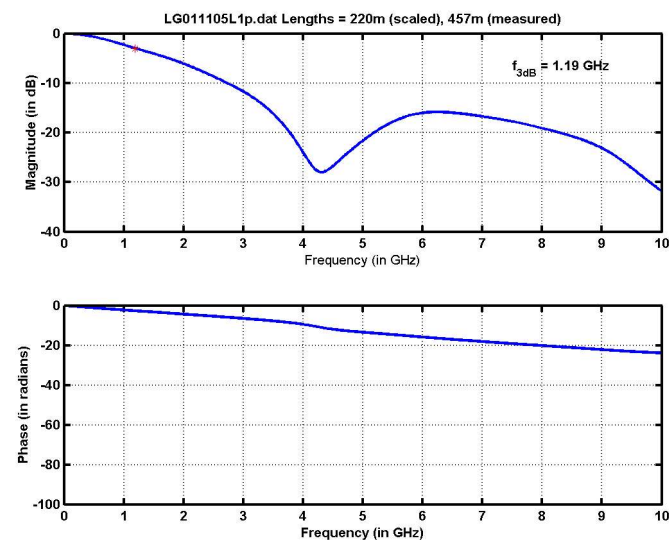
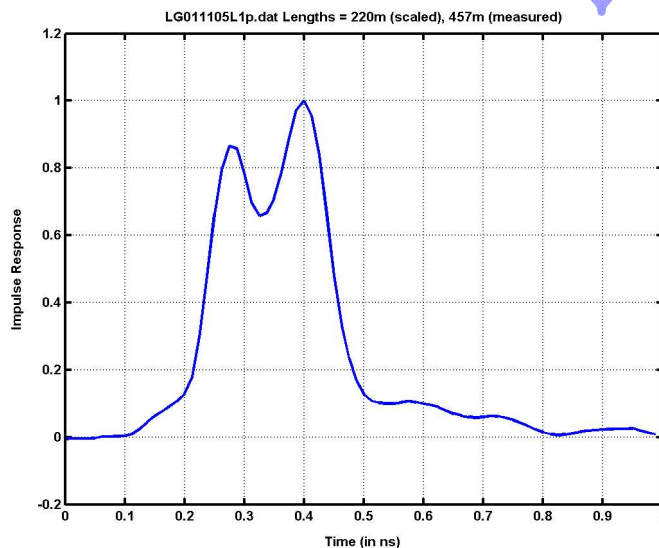
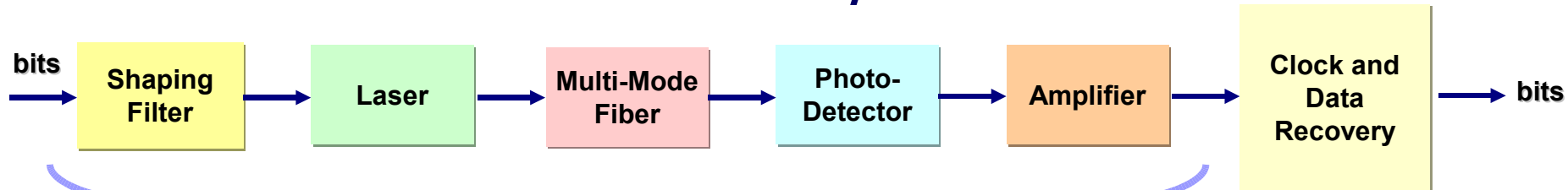


Efficient Estimation of Bit Error Rates and Eye Diagrams in Equalizer Enhanced Links

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Bit Error Rate Estimation in 10Gb/s LANs



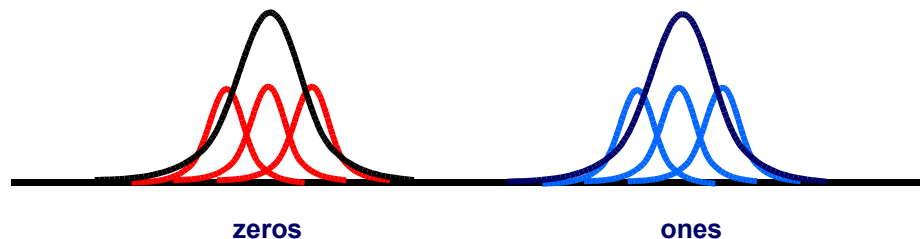
- Monte Carlo simulations are prohibitively long at a BER of 10^{-12} :
 - At least 100 errors for reliable BER estimation for an AWGN Channel
 - Need to transmit at least 10^{14} bits
 - Requires about 2.78 hours of real-time data at 10Gb/s
- Need to resort to BER estimation techniques

Method 1: Gaussian Approx. Approach

- **Model the ISI and the noise term together as AWGN**
- Assume 1's and 0's to be equally likely and independent
- Estimate means and standard deviations
 - at the zero rail (m_0, σ_0)
 - at the one rail (m_1, σ_1)
- Optimum Bit Error Rate (BER) and Threshold are then given by:

$$P_e = \frac{1}{2} \operatorname{erfc} \left(\frac{1}{\sqrt{2}} \left[\frac{m_1 - m_0}{\sigma_1 + \sigma_0} \right] \right) \quad D = \frac{m_0 \sigma_1 + m_1 \sigma_0}{\sigma_1 + \sigma_0}$$

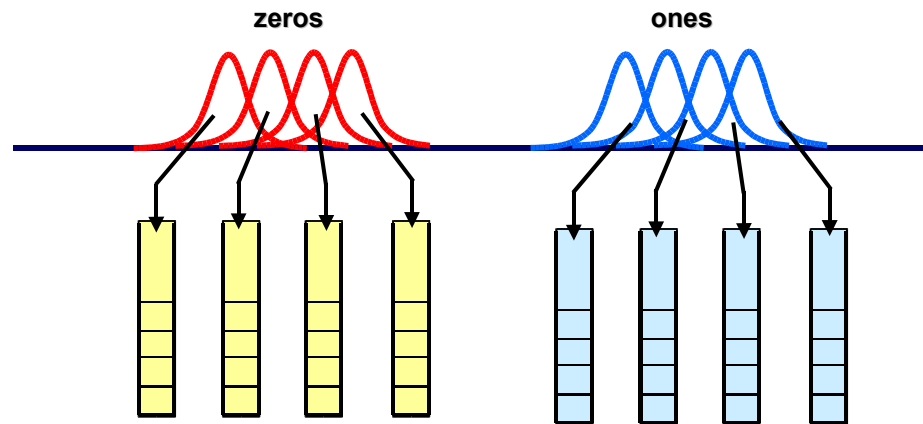
- **But in practice, input to decision device is the sum of Gaussians**
 - each corresponding to one combination of neighboring bits



- Hence BER estimate is not correct

Method 2: ISI Pattern Approach

- **Model input to the decision device as a sum of Gaussians**
 - **Mean of each Gaussian depends on the adjacent bits**



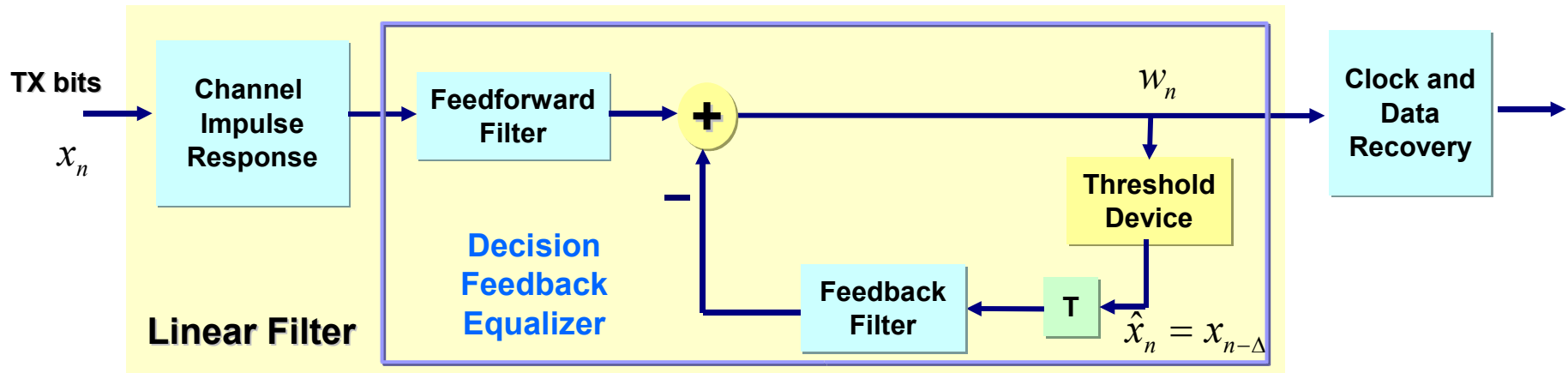
ISI due to 2 bits

- For each transmitted bit find the ISI pattern (or Gaussian) to which it belongs
- Estimate means and standard deviations of each Gaussian
- Bit Error Rate at a threshold D and channel span L is given by:

$$P_e = \frac{1}{2^L} \sum_{i \in S_0} \text{erfc} \left(\frac{D - m_i}{\sqrt{2}\sigma_i} \right) + \frac{1}{2^L} \sum_{i \in S_1} \text{erfc} \left(\frac{m_i - D}{\sqrt{2}\sigma_i} \right)$$

- **Complexity of Method 2 results in Long simulation times**
 - **increases exponentially with channel memory**
 - Also requires large number of bits to reliably estimate mean & std. deviation

Proposed Method: ISI Statistics Analytically



- Assume that there is no error propagation in the DFE
 - Usually valid at BERs lower than 10^{-5} ; we are operating at even lower BERs
 - Then $\hat{x}_n = x_{n-\Delta}$
 - x_n denotes the transmitted bit for the n th bit period and
 - Δ is an appropriately chosen delay
- **Entire system up to CDR is a linear filter with known coefficients!!**
 - System is from x_n to w_n
 - Ideal equalizer coefficients are determined based on channel response

Proposed Method contd.

- Thus the Input to the threshold device is:

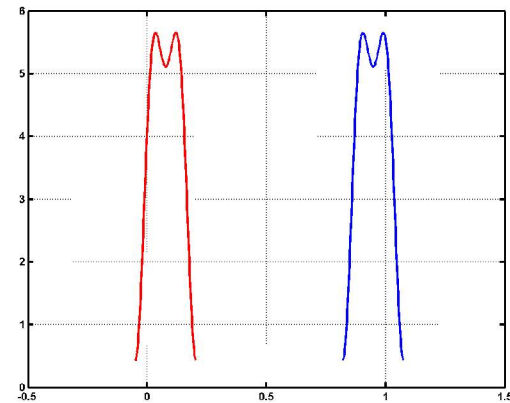
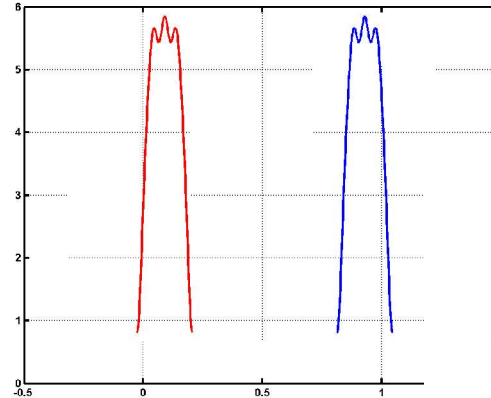
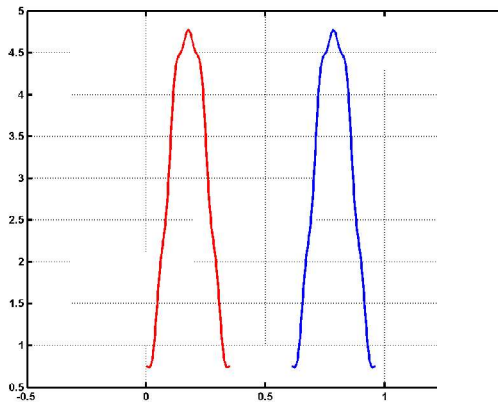
$$w_n = d_{\Delta} x_{n-\Delta} + r_n + v_n; \quad r_n = \sum_{i \neq \Delta} d_i x_{n-i}$$

- Where r_n corresponds to the residual ISI and v_n is the additive noise
- **Probability Density Function, $\hat{p}(r_n)$, of ISI can be computed analytically**
 - Since its Characteristic Function is a direct function of above coefficients
 - And the input alphabet statistics
- And so the minimum BER and optimum Threshold are given by:

$$P_e = \frac{1}{2} \int_{-\delta/2}^{\delta/2} p(y) \operatorname{erfc} \left(\frac{d_{\Delta}/2 - y}{\sqrt{2}\sigma} \right) dy; \quad D = \frac{d_{\Delta} + \sum_{i \neq \Delta} d_i}{2}$$

- Where $\delta = \sum_{i \neq \Delta} |d_i|$

Results: ISI Statistics

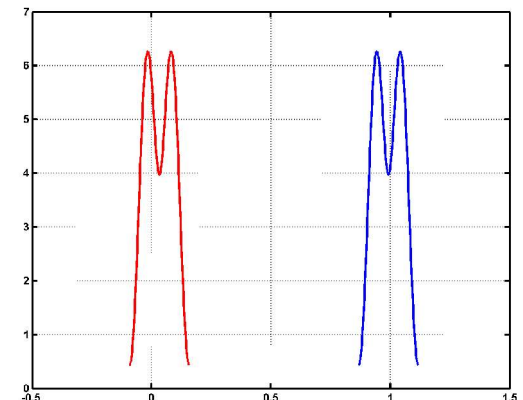


Red for zeros

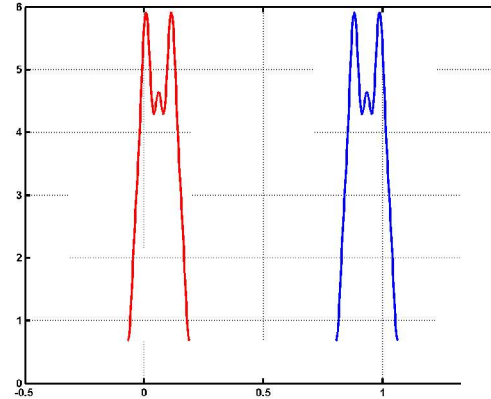
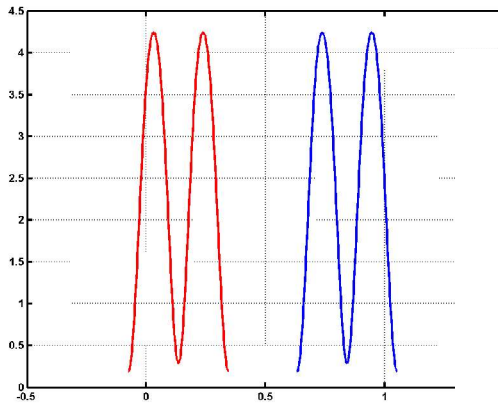
Blue for ones

Increasing SNR

- **Two feed-forward taps and One feedback tap**
- Probability Density Function of ISI at input to slicer
- Non-Impulsive nature of ISI PDF indicates significant residual ISI
- Non-Gaussian nature of ISI evident

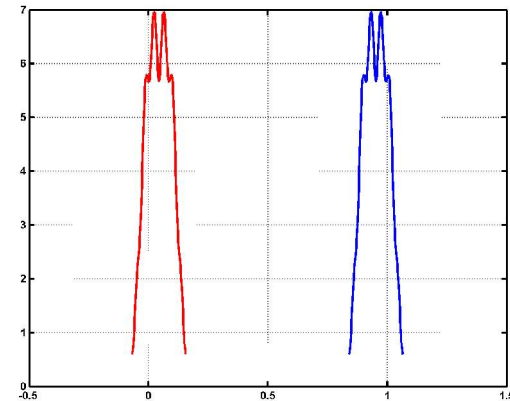


Results: ISI Statistics



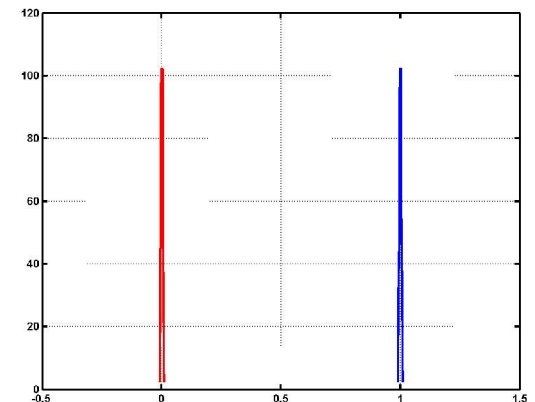
Red for zeros

Blue for ones

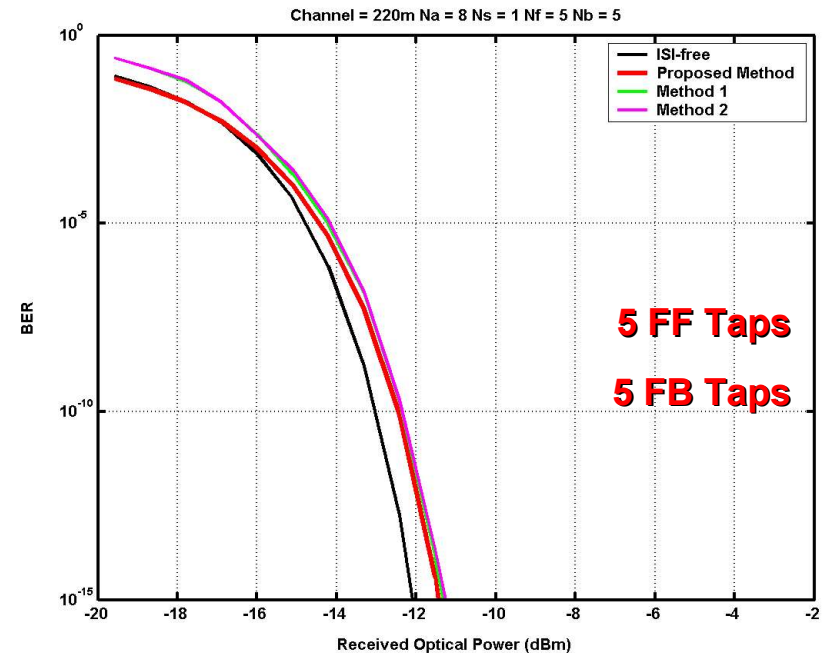
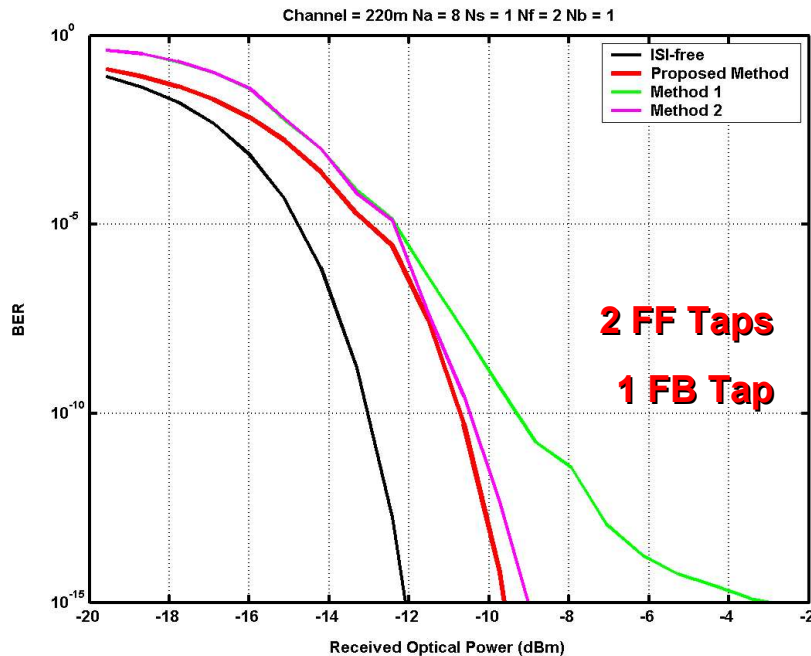


Increasing SNR

- **Five feed-forward taps and Five feedback taps**
- Non-Gaussian ISI at low TX powers
- Negligible ISI at high TX powers



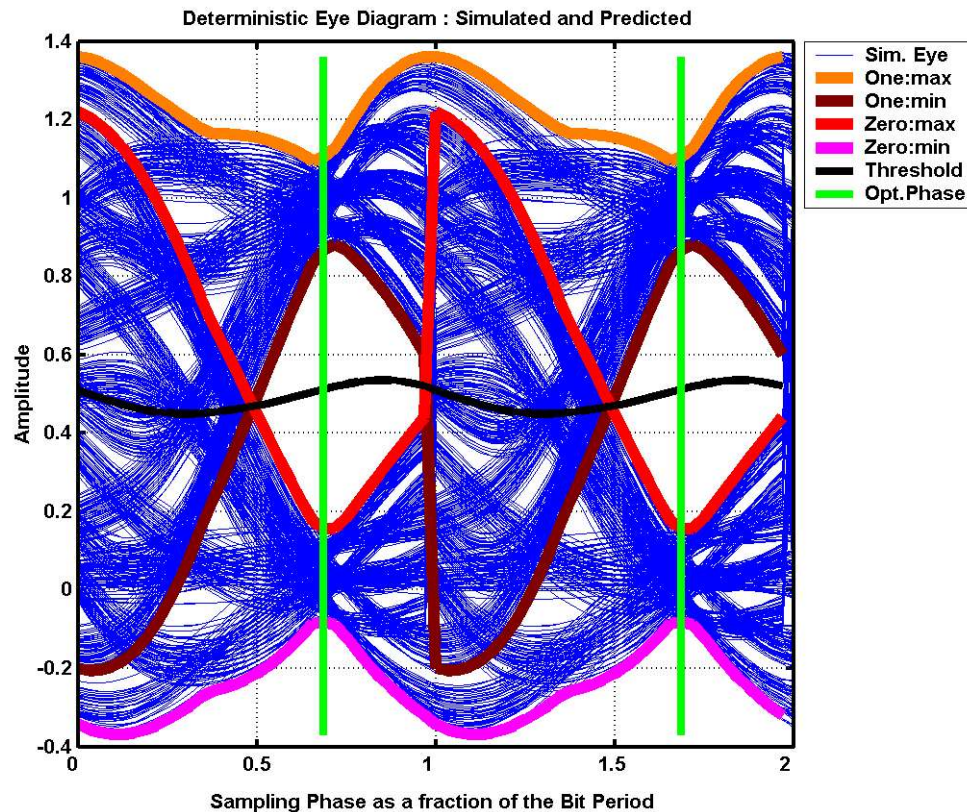
Results: BER Comparison



- 2 FF Taps + 1 FB Tap case:
 - Single Gaussian Approx. (Method 1) deviates significantly with fewer equalizer coefficients
 - Multiple Gaussian Approach (Method 2) better but still deviates
 - Since ISI is assumed to have contributions from only two adjacent bits
- 5 FF Taps + 5 FB Taps case:
 - Estimates from all three approaches agree at high sensitivities
 - Methods 1 & 2 still deviate at low sensitivities : ISI is not Gaussian in this regime
- **Proposed method is about 1000x times faster than Method 2 for all transmit powers!!**

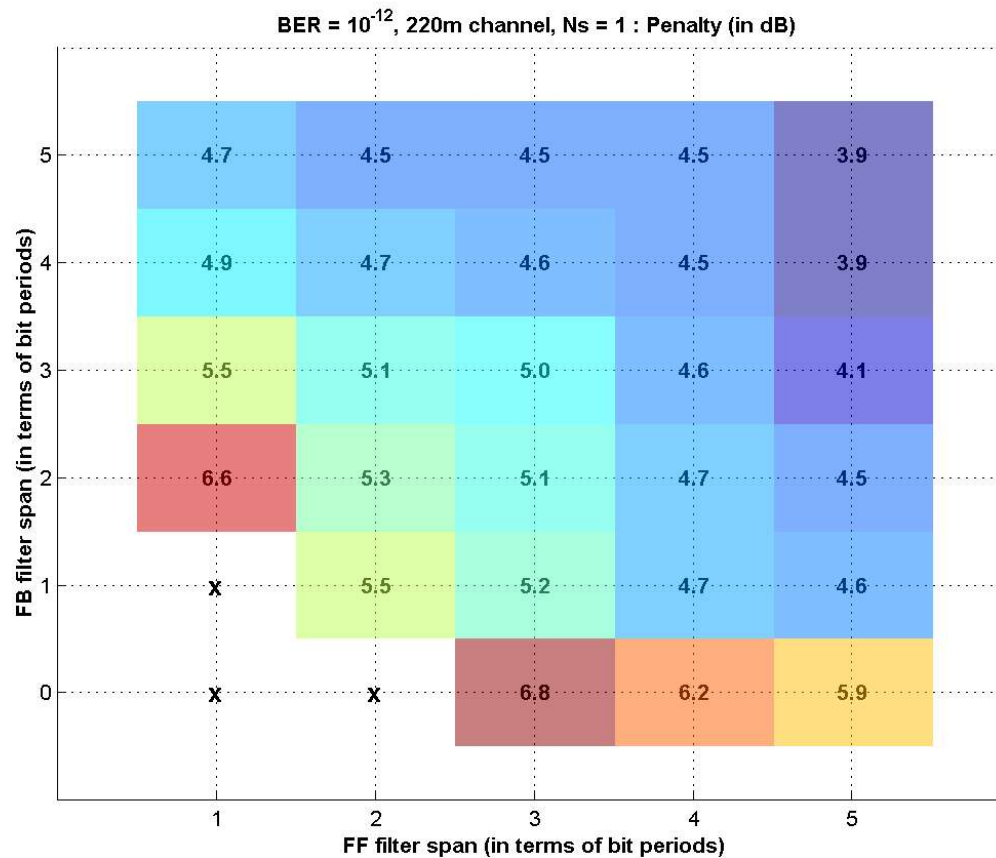
Estimation of Deterministic Eye Diagram

- For each sampling phase, noise-free input to slicer: $w_n = d_{\Delta}x_{n-\Delta} + \sum_{i \neq \Delta} d_i x_{n-i}$
- For each value of $x_{n-\Delta}$ (zero)
 - Maximum value of ISI = sum of all positive d_i
 - Minimum value of ISI = sum of all negative d_i
 - When $x_{n-\Delta} = \text{one}$, we need to add d_{Δ} to each max/min value
 - Both can be exactly computed
- Can be used to find optimum sampling instant and threshold also



Contour Plots

- Proposed technique can be used to quickly explore the equalizer design space via Contour Plots
- ISI Penalty = additional RX sensitivity required to achieve BER of 10^{-12}



- **An efficient BER estimation method has been proposed**
- Advantages:
 - **Accurate:**
 - More accurate than other methods when significant ISI is present
 - At least as accurate as other methods when ISI is negligible
 - Can even be applied at the input to the equalizer with accurate results
 - **complexity that increases linearly with channel memory**
 - As opposed to exponential complexity of Method 2
 - **about 1000x faster than other techniques**
 - **Independent of the equalizer adaptation technique**
- Permits easy estimation of the Deterministic Eye
 - Can also find optimum sampling instant and threshold
- Permits quick exploration of the equalizer design space