



► Marvell. Moving Forward Faster

# Synchronization State Machine Modification

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# Objectives

- ▶ Allow link up between forced 1000BASE-T1 PHY and Auto-Negotiation Enabled PHY
- ▶ Some house keeping for forced 1000BASE-T1 mode
- ▶ Consistent transition into training regardless of path taken
- ▶ Keep exchange of SEND\_S half duplex

# House keeping

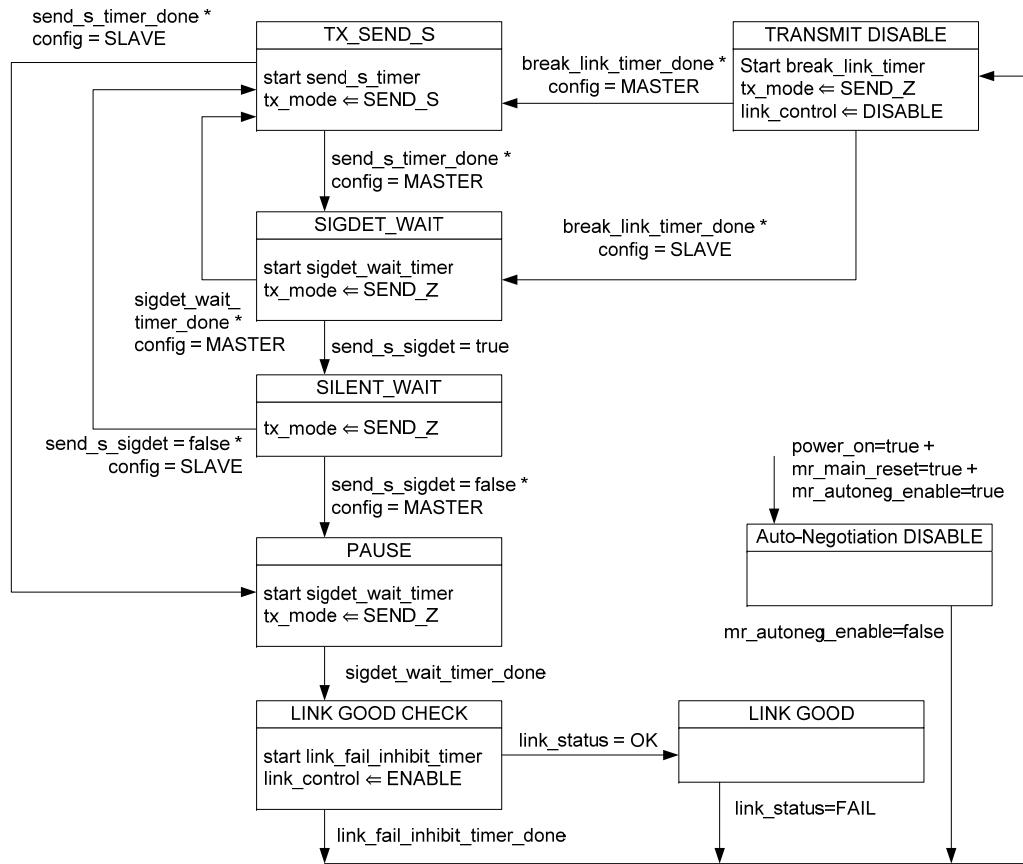
- ▶ If Auto-Negotiation is not implemented need registers to
  - Manually set master / slave
  - Manually tell the PHY that 1000BASE-T1 is selected
- ▶ Add following registers to control

Bit(s)	Name	Description	R/W
1.2304.4	Master/Slave	1 = Master 0 = Slave	R/W
1.2304.3:0	PHY Type	BASE-T1 PHY speed when Auto-negotiation is disabled 0000 = Reserved 0001 = Reserved 0010 = 1000BASE-T1 Else = Reserved	R/W

- ▶ Registers ignored if Auto-Negotiation is enabled
- ▶ See Lo\_McClellan\_3bp\_01a\_0315.pdf page 1 for detail text
  - 1.2304.4 is force\_config variable
  - 1.2304.3:0 is force\_phy\_type variable

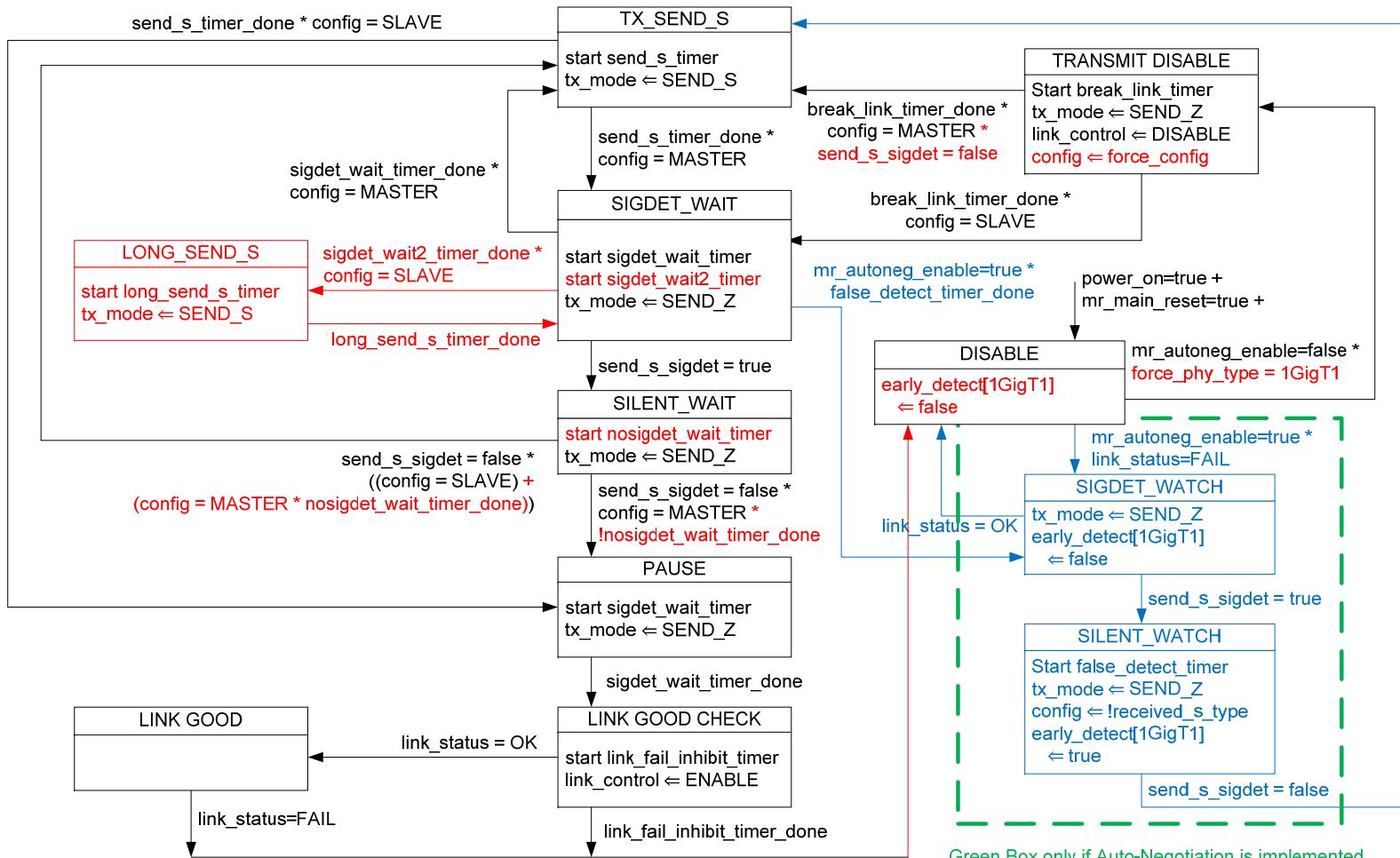
# Current Synchronization State Machine

- ▶ Forced slave is always silent
  - No way for link partner to know the slave PHY is there.



# Proposed Updates

- Slave is not silent all the time (**LONG\_SEND\_S**)
- Orderly path to allow transition from Auto-Neg to Sync State Machine (Blue states)



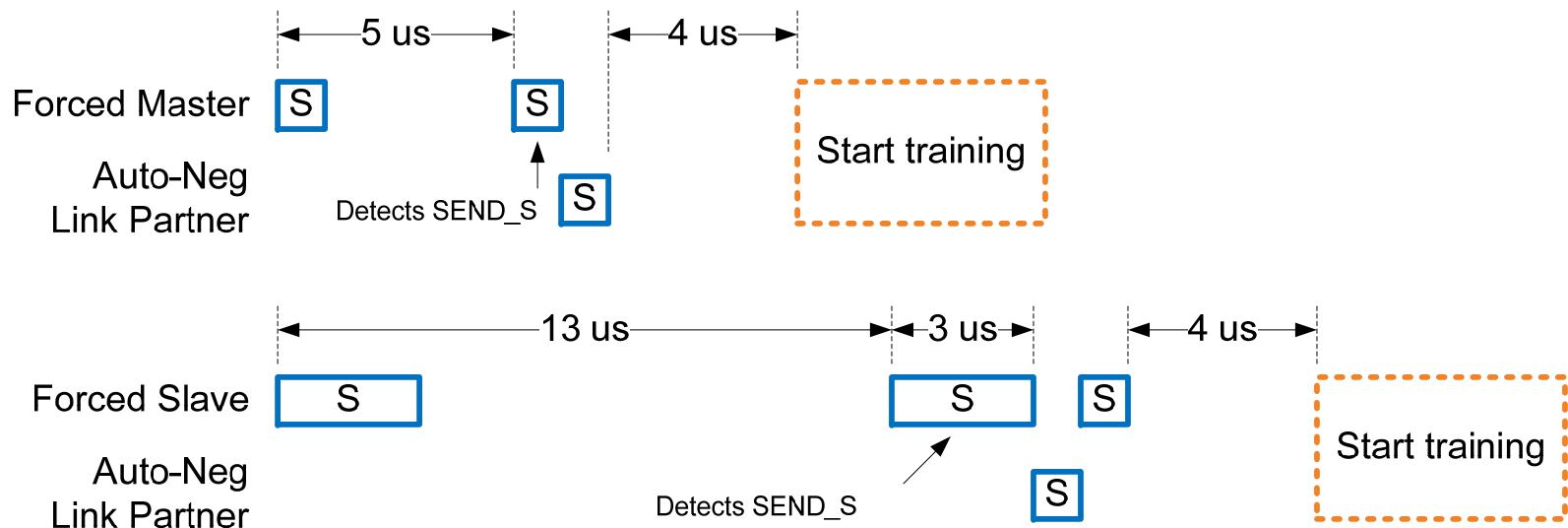
# Timers for synchronization

- ▶ Preserves half duplex nature of SEND\_S
- ▶ Slave sends longer duration SEND\_S only for the purpose to wake Auto-Negotiation enabled link partner
- ▶ Synchronize only on normal duration SEND\_S (both master and slave)

Timer	Duration	Description
send_s_timer	1.0us +/- 0.04us	Normal SEND_S duration
sigdet_wait_timer	4.0us +/- 0.04us	Time between end of one SEND_S and beginning of next SEND_S from master if slave does not respond
long_send_s_timer	3.0us +/- 0.04us	Long SEND_S duration from slave used to wakeup link partner
sigdet_wait2_timer	10.0us +/- 0.04us	Time between end of one SEND_S and beginning of next SEND_S from slave if master does not respond
nosigdet_wait_timer	1.7us +/- 0.04us	Timer for master to test whether normal or long duration SEND_S is sent by slave
false_detect_timer	10.0us +/- 0.04us	Exit timer if false detection triggered.

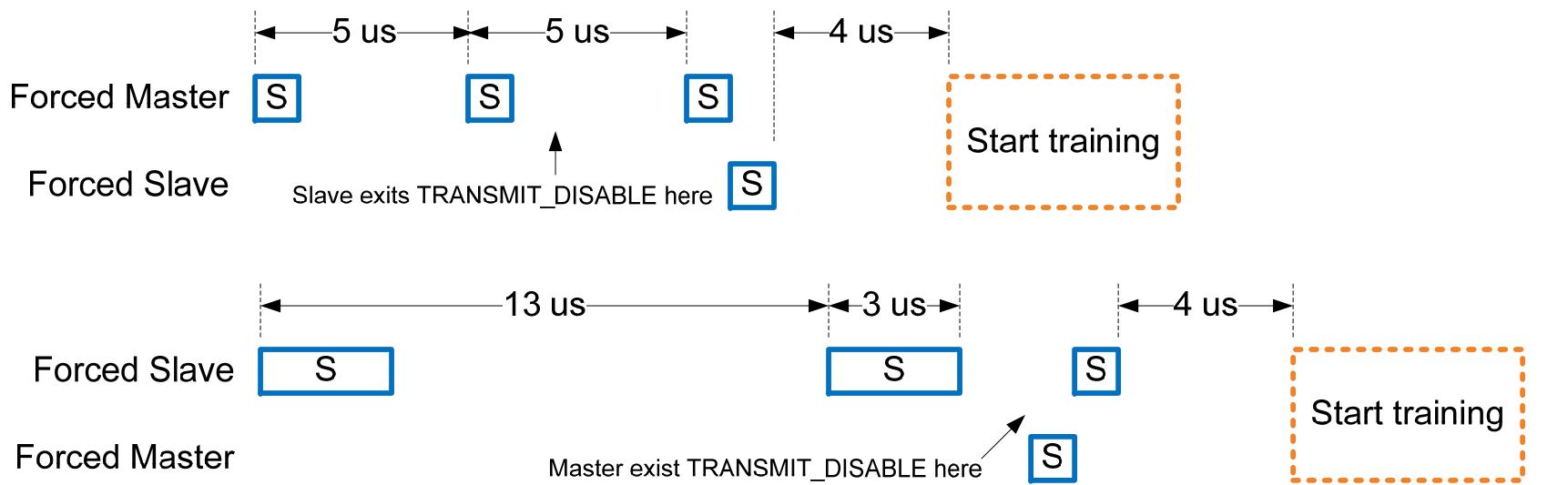
# Scenario: Force one side, Auto-Negotiation on other side

- ▶ **SIGDET\_WATCH:** Watch for **SEND\_S**
- ▶ **SILENT\_WATCH:** Watch for **SEND\_S** to end
- ▶ **TX\_SEND\_S:** Transmit **SEND\_S** and continue as normal
- ▶ **Consistent start up – Slave always transmits final **SEND\_S****



## Scenario: Both sides forced, no SEND\_S collision

- Slave sees master's SEND\_S first and responds with its own SEND\_S
- Long duration SEND\_S does not interfere
- Slave always the last to transmit SEND\_S



# Scenario: Both sides forced, SEND\_S collision

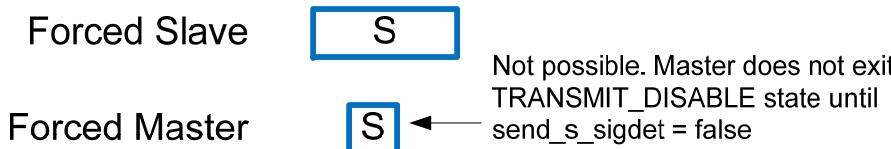
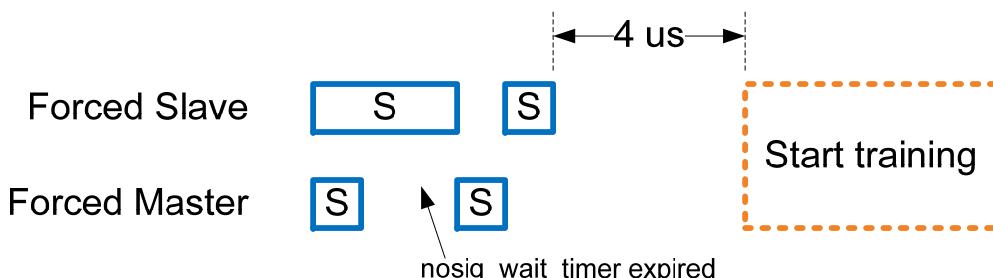
- Both side initiates SEND\_S simultaneously

## Master Path:

- TX\_SEND\_S – Send normal duration SEND\_S
- SIGDET\_WAIT – sees slave's SEND\_S
- SILENT\_WAIT – nosigdet\_wait\_timer expires
- TX\_SEND\_S – long duration SEND\_S from slave doesn't count

## Slave Path:

- Long\_SEND\_S – Send long duration SEND\_S
- SIGDET\_WAIT - waits for master's SEND\_S
- SILENT\_WAIT – waits for master to be quiet
- TX\_SEND\_S – Send normal duration SEND\_S

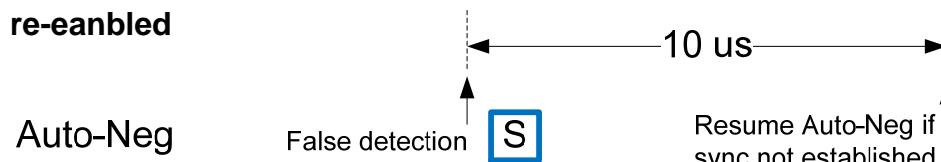


- Collisions always start simultaneously
- Cannot transmit SEND\_S unless there is no signal detect

# Other Scenarios

## ▶ False detection:

- **SIGDET\_WATCH** – false detection
- **SILENT\_WATCH** - starts **false\_detect\_timer**
- **TX\_SEND\_S** – Send normal duration **SEND\_S**
- **SIGDET\_WAIT** – no resolution,  
**false\_detect\_timer** expires
- **SIGDET\_WATCH** – Auto-Neg re-enabled



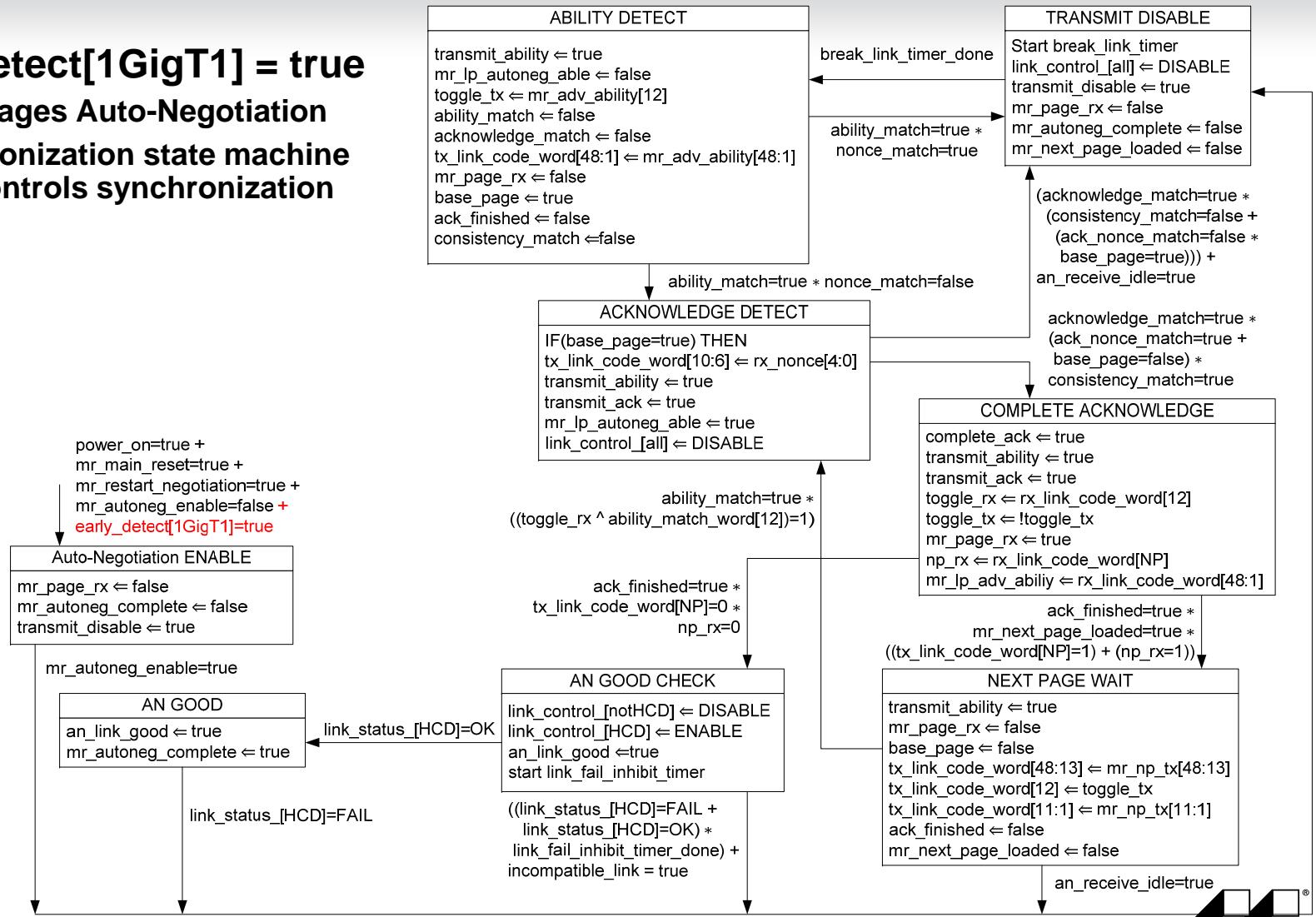
## ▶ Auto-Negotiation on both sides:

- **SIGDET\_WATCH** – watching link partner
- **DISABLE** - enters here when link is up via Auto-Negotiation

Can shut down **SEND\_S** detection circuit

# Auto-Negotiation Arbitration State Machine

- ▶ **early\_detect[1GigT1] = true**
  - Disengages Auto-Negotiation
  - Synchronization state machine fully controls synchronization



# New variables 97.6.1.1 and timers 97.6.1.2

## Variables

force_config	Master/slave configuration when Auto-Negotiation is disabled Values      MASTER SLAVE
force_phy_type	BASE-T1 Type configuration when Auto-Negotiation is disabled Values      1GigT1: Select 1000BASE-T1 type
early_detect[1GigT1]	See 98.5.1
received_s_type	SEND_S type of link partner. If received_s_type is MASTER then !received_s_type is SLAVE and vice versa. Values      MASTER SLAVE

## Timers

long_send_s_timer	Timer used to control the long duration SEND_S is transmitted by slave The timer shall expire 3.0us ±0.04 us after being started.
signal_wait2_timer	Timer used by the slave to control the wait time between transmitting long duration SEND_S. The timer shall expire 10.0us ±0.04 us after being started.
nosigdet_wait_s_timer	Timer used by the master to test whether the SEND_S from the slave is normal or long duration. The timer shall expire 1.7us ±0.04 us after being started.
false_detect_timer	Exit timer if false SEND_S.detection is triggered The timer shall expire 10.0us ±0.04 us after being started.

# New variables 98.5.1

## Variables

early\_detect[x]

Early detection that link can operate in x type.

Values      True: detection that link can operate in x type.

False: no detection that link can operate in x type.

# THANK YOU