Comment discussion: Clause 162

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TX Presets

Comment Summary

C#	Summary	Notes
103	Add control field bit to expand the # of presets to 7	
104	Define initial coefficient pre-set values	Presentation forthcoming
143	Specify values for transmit presets 2 & 3, and set tolerance to +/-0.025	Tolerance consistent with Table 162-9.
142	Allocate MDIO registers to hold coefficient values for OUT_OF_SYNC (instead of fixed values), with [0 0 0 1 0] default values (Preset 1)	Presentation forthcoming

These comments primarily pertain to Table 162-10

Full Comment Text

An expand and of predefined equations eatings would be useful. The ability is select an inside condition corpor to Proposed and Confusion of proper to Proposed sellings can be expected to improve robustness and decrease the confusion of proper to proper the selling can be expected to improve robustness and decrease the confusion of proper to proper the expected part to proper the confusion of proper to proper the expected part to proper the confusion of proper to proper the expected part to proper the confusion of proper to proper the proper to proper the proper to proper the proper to proper the proper to proper to proper the proper to proper the proper to proper to proper the proper to p	Comm	Commen terName	Clause =	Subclause =	Page −	Line =	Comm entTyp e —	Comment	SuggestedRemedy —	Response -
Healey, Adam 162 162.9.3.1.3 151 30 T T in Tables 162-10, the coefficient initial conditions for presets 2 and onward are TBD. Cross-disuse The OUT_CF_SYNC setting is the initial setting used when bringing up a link. It is likely not the optimal setting many cases, and many not be a good starting which can be a good starting which cases, and many notice and the coefficient initial setting many be preferable. To neather fast live in such cases, for the proposed mat the coefficient initial setting may be preferable. To neather fast live in such cases, for the proposed mat the coefficient in the coefficient initial setting may be preferable. To neather fast live in such cases, for the proposed mat the coefficient initial setting may be preferable. To reache fast live in such cases, for the proposed mat the coefficient initial setting may be preferable. To reache fast live in such cases, for the proposed mat the coefficient initial setting may be preferable. To reache fast live in such cases, for the proposed mat the coefficient initial conditions (gresentation with solid in the values that will be set in OUT_OF_SYNC. The neather fast live in such cases, for the values of the common that the coefficient initial conditions of the values that will be set in OUT_OF_SYNC. Two new sets of RW registers should be allocated. Each set corresponds to the Scotlands of the values that will be set in OUT_OF_SYNC. The neather fast live in the values that will be set in OUT_OF_SYNC. The coefficient values, one register each. Total of the values that will be set in OUT_OF_SYNC. Current coefficient values, one register each. Total of the values that will be set in OUT_OF_SYNC. Current coefficient values, one register each. Total of the values that will be set in OUT_OF_SYNC. Current coefficient values, one register each. Total of the values t	103	Healey, Adam	162	162.8.11		27	т	The ability to select an initial condition closer to the target settings can be expected to improve robustness and decrease training time (due to a reduction in the number of iterative	condition request" to enable the definition of up to 7 presets with encoding 000 being "Individual coefficient control". The equalizer settings corresponding to each preset will be specified	
The OUT_OF_SYNC setting is the initial setting used when birriging up a link. It is fixely not the options setting in many cases, and may not be a good starting point, which can cause long link-up times. In cases where the channel and link partner are known (typical in backplane or C2C), another initial setting may be preferable. To retable fast link up in such cases, it is proposed that the registers is completed of being from Cases. It is completed in the channel is completed of being from Cases. It is completed in the channel is unknown the behavior is unchanged from D1.2. Ran, Adee 162 162.9.3.1.3 151 30 T T some the carried present of setting food of the dead it values of the registers will create the current present 1 settings [0.0.0.1.0], so that when the channel is unknown the behavior is unchanged from D1.2. (cross-clause) Transmitter presents 2 and 3 are currently TBDs. It is proposed to use these presents as starting point for high-rises and low-loss channels. Preset 2 in the suggested remedy is based on COM simulations of 2 m cable + 2*110m m host board, and 1.5 m cable + 2*05 host board, and as everall backplane channels (results are quite similar). Preset 3 for in the suggested remedy is aimed at short reach channels from or relevant for backplane(C2C), has minimum (0) assumed in COM and no equalization, for channels that may need reduced swing. Even if equalization is required, this can be used as a convenient starting point of an optimization aggretion. Preset are based on the maximum allowed step size of 2.5% and should have a tolerance of one step. Preset 2: 0.025, 0.075, -0.25, 0.85, 0 Preset 2: 0.025	104	Healey, Adam	162	162.9.3.1.3	151	30	т			Pending review of the following presentation: http://www.ieee802.org/3/ck/public/20_07/healey_3ck_01_07 20.pdf
Transmitter presets 2 and 3 are currently TBDs. It is proposed to use these presets as starting points for high-loss and low-loss channels. Preset 2 in the suggested remedy is based on COM simulations of 2 m cable + 2*110 mm host board, and 1.5 m cable + 2*55 host board, and several backplane channels (results are quite similar). Preset 3 for in the suggested remedy is aimed at short reach channels (more relevant for backplane/C2C), has minimum c(0) assumed in COM and no equalization, for channels that may need reduced swing. Even if equalization is required, this can be used as a convenient starting point of an optimization algorithm. Change the TBD values in the table as follows: Preset 3: -0.025, 0.075, -0.25, 0.65, 0 Preset 3: -0.025, 0.075, -0.25, 0.65, 0	142	Ran, Adee	162	162.9.3.1.3	151	30	т	The OUT_OF_SYNC setting is the initial setting used when bringing up a link. It is likely not the optimal setting in many cases, and may not be a good starting point, which can cause long link-up times. In cases where the channel and link partner are known (typical in backplane or C2C), another initial setting may be preferable. To enable fast link up in such cases, it is proposed that the coefficients in OUT_OF_SYNC state be taken from MDIO registers instead of being fixed. The default values of the registers will create the current preset 1 settings [0 0 0 1 0], so that when the channel is unknown the behavior is unchanged	corresponds to the 5 coefficient values, one register each. "Initial coefficient vector" hold the values that will be set in OUT_OF_SYNC. "Current coefficient vector" holds the current coefficients. The encoding of these registers is implementation dependent, but is consistent between the sets.	Pending presentation & Task force discussion. The referenced presentation is here.
Clause 163 and Annex 120F do not have explicit settings but Set tolerance of +/- 0.025 for all presets (including preset 1 and								(cross-clause) Transmitter presets 2 and 3 are currently TBDs. It is proposed to use these presets as starting points for high-loss and low-loss channels. Preset 2 in the suggested remedy is based on COM simulations of 2 m cable + 2*110 mm host board, and 1.5 m cable + 2*55 host board, and several backplane channels (results are quite similar). Preset 3 for in the suggested remedy is aimed at short reach channels (more relevant for backplane/C2C), has minimum c(0) assumed in COM and no equalization, for channels that may need reduced swing. Even if equalization is required, this can be used as a convenient starting point of an optimization algorithm. Presets are based on the maximum allowed step size of 2.5% and should have a tolerance of one step.	Change the TBD values in the table as follows: Preset 2: -0.025, 0.075, -0.25, 0.65, 0 Preset 3: 0, 0, 0, 0.525, 0	Accept in principle

C#103 Specifics

SuggestedRemedy

Add bit 11 of the control field (currently reserved) to "Initial condition request" to enable the definition of up to 7 presets with encoding 000 being "Individual coefficient control". The equalizer settings corresponding to each preset will be specified in 162.9.3.1.3 as already stated.

Changes:

- New Exceptions added to 162.8.11
 - Table 136-9 amended as shown to the right
 - UPDATE_IC to apply new presets (slide 5 healey 3ck 01 0720.pdf)
- Modify an existing exception in 162.8.11
 - 136.8.11.2.1 Initial Condition request (add 3b select field to the exception)
- Expand Table 162-10 to cover additional presets.

Bit			Coloct		
13	12	11	Select		
1	1	1	Reserved		
1	1	0	Reserved		
1	0	1	PRESET5		
1	0	0	PRESET4		
0	1	1	PRESET3		
0	1	0	PRESET2		
0	0	1	PRESET1		
0	0	0	Individual coefficient control		

C#104 and 143

• Update Table 162-10 to be

Coefficient update State	ic_req	c(-3)	c(-2)	c(-1)	c(0)	c(1)
OUT_OF_SYNC ^a	N/A	0	0	0	1	0
NEW_IC	PRESET1 ^a	0	0	0	1	0
	PRESET2	0 ± 0.0125	0 ± 0.0125	0 ± 0.0125	0.50 ± 0.0125	0 ± 0.0125
	PRESET3	0 ± 0.0125	0 ± 0.0125	-0.075 ± 0.0125	0.75 ± 0.0125	0 ± 0.0125
	PRESET4	0 ± 0.0125	0.050 ± 0.0125	-0.200 ± 0.0125	0.75 ± 0.0125	0 ± 0.0125
	PRESET5	-0.025 ± 0.0125	0.075 ± 0.0125	-0.250 ± 0.0125	0.65 ± 0.0125	0 ± 0.0125

^a PRESET1 is the reference for the calculation of the normalized coefficients of the transmit equalizer (see 162.9.3.1.1). As a result the normalized coefficients for PRESET1 and OUT_OF_SYNC do not include any tolerances.

The setting of the Tx FIR in the OUT_OF_SYNC state in Figure 136-9 is scattered across the clause. However, the changes suggested in healey 3ck 01 0720.pdf would also require a modification to Figure 136-9 to maintain ic sts = not upd being sent while in this state.

C#142

- Suggests making the OUT_OF_SYNC TX FIR setting be programmable to assist in reducing link up time. Along with stating a presentation will be provided.
- No presentation has been provided
- Upon starting the PMD Control function process per 136.8.11.4.2 the TX FIR is set to PRESET1 (noEq full swing).
- PRESET1 allows for easy acquisition of training frame lock across a variety of channels. It's also a known starting point from which an adaptation algorithm can begin from.
- C#103 and 104 have added 2 new PRESET Tx FIR settings which adaptation algorithms can make use of to evaluate which one to begin micro-adjusting from. Note, there are currently 2 settings left as unused at this time.
- Depending upon the adaptation algorithm seeding the startup TX FIR with a known good setting may not reduce time to link up.