

# ACT text proposal for IEEE 802.3dm

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200 Physical Coding Sublayer (PCS), Physical Medium Attachment (PMA) sublayer, and baseband medium, type 100M+2.5GMBASE-T1, 2.5G+100MBASE-T1, 100M+5GBASE-T1, 5G+100MBASE-T1, 100M+10GBASE-T1, 10G+100MBASE-T1, 100M+2.5GBASE-V1, 2.5G+100MBASE-V1, 100M+5GBASE-V1, 5G+100MBASE-V1, 100M+10GBASE-V1, 10G+100MBASE-V1

*This is a draft proposal for how a Clause could be structured based on the P802.3dm project documents, including Objectives. This provides flexibility to have different requirements for the different speeds and cabling. Subclauses can be combined later if the requirements are the same, or the requirement can be put in the first subclause in the document and the one later in the document can refer back to it.*

*Due to the fact that we are limited to a maximum of five levels in the specification, the high speed and low speed requirements are in separate subclauses without a subsection above the pair. This is also the case for the coax and shielded balanced copper cabling.*

## 200.1 Overview

*May be added by Editor based on project details.*

### 200.1.1 Nomenclature

*May be added by Editor based on project details.*

*In order to efficiently describe the three PHYs, the nomenclature MultiG is used to abbreviate 2.5G/5G/10G when referring to the set of PHYs.*

### 200.1.2 PHY/PMD types

*I have included a table here to show the different PHYs to be defined and what all the characters that I am using in the names mean. These are subject to approval.*

x+y – x is the transmit speed, y is the receive speed

T1 – single shielded balanced pair of conductors (SBP)

V1 – single coaxial cable (Coax)

PHY name	Transmit speed	Receive speed	Cable type
100M+2.5GBASE-T1	100M	2.5G	SBP
2.5G+100MBASE-T1	2.5G	100M	SBP
100M+5GBASE-T1	100M	5G	SBP
5G+100MBASE-T1	5G	100M	SBP
100M+10GBASE-T1	100M	10G	SBP
10G+100MBASE-T1	10G	100M	SBP
100M+2.5GBASE-V1	100M	2.5G	Coax
2.5G+100MBASE-V1	2.5G	100M	Coax
100M+5GBASE-V1	100M	5G	Coax
5G+100MBASE-V1	5G	100M	Coax
100M+10GBASE-V1	100M	10G	Coax
10G+100MBASE-V1	10G	100M	Coax

When talking about all high speed transmit PHYs, regardless of cable type, use:

*MultiG+100MBASE-T1/V1.*

When talking about all low speed transmit PHYs, regardless of cable type, use:

*100M+MultiGBASE-T1/V1.*

When talking about all PHYs communicating on shielded, balanced, pair of conductors, regardless of transmit speed, use:

*MultiG+100M/100M+MultiGBASE-T1*

When talking about all PHYs communicating on coaxial cable, regardless of transmit speed, use:

*MultiG+100M/100M+MultiGBASE-V1*

When talking about all PHYs, regardless of transmit speed or cable type, use:

*MultiG+100M/100M+MultiGBASE-T1/V1*

200.1.3 Relationship of **MultiG+100M/100M+MultiGBASE-T1/V1** to other standards  
May be added by Editor based on project details.

#### 200.1.4 Operation of MultiG+100M/100M+MultiGBASE-T1/V1

*Summary provided by contribution later in project*

##### 200.1.4.1 Physical Coding Sublayer (PCS), MultiG+100MBASE-T1/V1

For the high data rate direction, the MultiG+100MBASE-T1/V1 PCS couples a 10 Gigabit Media Independent Interface (XGMII), as specified in 46, to the 2.5G+100MBASE-T1/V1, 5G+100MBASE-T1/V1, or 10G+100MBASE-T1/V1 Physical Medium Attachment (PMA) sublayer. In addition to the normal mode of operation, the PCS supports a training mode. Furthermore, the PCS contains a management interface.

In the high data rate direction, the PCS functions as specified in 149.

##### 200.1.4.2 Physical Coding Sublayer (PCS), 100M+MultiGBASE-T1/V1

In the **low data rate** direction, in normal mode, the PCS receives eight XGMII data octets provided by two consecutive transfers on the XGMII service interface on TXD<31:0> and groups them into 64-bit blocks with the 64-bit block boundaries aligned with the boundary of the two XGMII transfers. Each group of eight octets along with the data/control indications is transcoded into a 65-bit block.

These 65-bit blocks are then aggregated into groups of 4 blocks. The contents of each group are contained in a vector tx\_group4x65B. Next, a 16-bit OAM/Reserved field is appended to form a 276-bit block. Each of these 276 bit blocks is formed into an RS-FEC input frame, then encoded by the RS-FEC (50,46,6). The RS-FEC output superframe consists of 300 bits. The duration of the frame is 2560 ns. Finally, these bits are exclusive OR'd with a 33-bit self-synchronizing scrambler to create the 100M+MultiGBASE-T1/V1 payload. The low data rate direction PCS transmit functions are described in 200.3.2.2.

The tx\_group4x65B <259:0> is defined as:

$$\text{tx\_group4x65B} \langle 65 \times i + j \rangle = \text{tx\_coded} \langle j \rangle$$

where  $i = 0$  to  $3$ ,  $j = 0$  to  $64$ , and tx\_coded<64:0> is the  $i$ -th 64B/65B block where tx\_coded0<64:0> is the first block transmitted.

In the training mode (see 200.4.2.4), the PCS transmits and receives DME training frames to synchronize to the PHY frame (and exchanges EEE and 100M+MultiGBASE-T1/V1 OAM capabilities).

Details of the PCS functions and state diagrams are covered in 200.3. The interface to the PMA is an abstract message-passing interface specified in 200.4.

##### 200.1.4.3 Physical Medium Attachment (PMA) sublayer, MultiG+100MBASE-T1/V1

The PMA couples messages from the PCS service interface onto single balanced pair of conductors (T1) or single coaxial cables (V1) via the Medium Dependent Interface (MDI) and provides the link management and PHY Control functions.

The PMA provides asymmetric data rate communications with  $5625 \times S$  MBd high speed and 117.1875 MBd low speed. See Table 200–1 for the definition of  $S$ . The PMA PHY Control function generates signals that control the PCS and PMA sublayer operations. PHY Control is enabled following the completion of Auto-Negotiation or PHY Link Synchronization and provides the startup functions required for successful

MultiG/100M-BASE-T1 operation. It determines whether the PHY operates in a disabled state, a training state, or a data state where MAC frames can be exchanged between the link partners.

The Link Monitor determines the status of the underlying link channel and communicates this status to other functional blocks. A failure of the receive channel causes the data mode operation to stop and Auto-Negotiation or Link Synchronization to restart.

PMA functions and state diagrams are specified in 200.6 and 200.7. The electrical parameters of the PMA, i.e., test modes and electrical specifications for the transmitter and receiver, are specified in 200.8 and 200.9.

The PMA functions for the high data rate direction are as specified in 149.4 with the exceptions in this clause.

#### 200.1.4.4 Physical Medium Attachment (PMA) sublayer -L

*NOTE: It is probably sufficient to have single section for low speed and high speed for this section.*

#### 200.1.4.5 EEE Capability

*May want to include and indicate there is no EEE Capability if it is decided this is not needed/required/desired.*

#### 200.1.4.6 Link Synchronization

The Link Synchronization function is used when Auto-Negotiation is disabled or not implemented to detect the presence of the link partner, time and control link failure, and act as the data source for the PHY control state diagram. Link Synchronization operates in a half-duplex fashion. Link Synchronization is defined in <REF>.

#### 200.1.4.7 Link Synchronization

*NOTE: This section is probably redundant since there should be single section for low speed and high speed.*

### 200.1.5 Signaling, MultiG+100MBASE-T1/V1

MultiG+100MBASE-T1/V1 signaling is performed by the PCS generating continuous code-group sequences that the PMA transmits over single balanced pair of conductors (T1) or single coaxial cable (V1). The signaling scheme achieves a number of objectives including:

- a) Forward error correction (FEC) coded symbol mapping for data.
- b) Algorithmic mapping from TXD<31:0> and TXC<3:0> to PAM2 symbols in the 2.5Gb/s and 5Gb/s transmit path, and PAM4 symbols in the 10Gb/s high-speed transmit path.
- c) Algorithmic mapping from the received signal on the MDI port to RXD<31:0> and RXC<3:0>.
- d) Uncorrelated symbols in the transmitted symbol stream.
- e) No correlation between symbol streams traveling both directions.
- f) Block framing and other control signals.
- g) Ability to signal the status of the local receiver to the remote PHY to indicate that the local receiver is not operating reliably and requires retraining.

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- h) Ability to automatically detect and correct for incorrect polarity in the connection.
- i) Optionally, ability to support refresh, quiet, and alert signaling during LPI operation.

The PHY may operate in three basic modes: the normal data mode, the training mode, or an optional LPI mode.

In high speed direction, the PCS operates according to Clause 149, with the exception that 2.5Gb/s and 5Gb/s use PAM2 mapping instead of PAM4 mapping.

#### 200.1.6 Signaling, 100M+MultiGBASE-T1/V1

100M+MultiGBASE-T1/V1 signaling is performed by the PCS generating continuous code-group sequences that the PMA transmits over single balanced pair of conductors (T1) or single coaxial cable (V1). The signaling scheme achieves a number of objectives including:

- a) Forward error correction (FEC) coded symbol mapping for data.
- b) Algorithmic mapping from TXD<31:0> and TXC<3:0> to DME symbols in the high speed transmit path.
- c) Algorithmic mapping from the received signal on the MDI port to RXD<31:0> and RXC<3:0>.
- d) Uncorrelated symbols in the transmitted symbol stream.
- e) No correlation between symbol streams traveling both directions.
- f) Block framing and other control signals.
- g) Ability to signal the status of the local receiver to the remote PHY to indicate that the local receiver is not operating reliably and requires retraining.
- h) Ability to automatically detect and correct for incorrect polarity in the connection.
- i) Optionally, ability to support refresh, quiet, and alert signaling during LPI operation.

The PHY may operate in two basic modes: the normal data mode or the training mode.

In low speed direction and normal mode, the PCS generates a continuous stream of DME symbols that are transmitted via the PMA. In training mode, the PCS is directed to generate only TBD\_training symbols for transmission by the PMA. (See Figure <REF>)

#### 200.1.7 Interfaces

All MultiG+100M/100M+MultiGBASE-T1/V1 PHY implementations are compatible at the MDI and at the XGMII, if implemented. Implementation of the XGMII is optional. Designers are free to implement circuitry within the PCS and PMA in an application-dependent manner provided that the MDI and XGMII (if the XGMII is implemented) specifications are met. System operation from the perspective of signals at the MDI and management objects are identical whether the XGMII is implemented or not. The MDI for single balanced pair of conductors (T1) or single coaxial cable (V1), are different.

#### 200.1.8 Conventions in this clause

*Standard text*

#### 200.2 MULTIG+100MBASE-T1/V1 service primitives and interfaces

Service primitives and interfaces the high speed direction are as described in Clause 149.2.

200.3 100M+MultiGBASE-T1/V1 service primitives and interfaces, low speed channel  
100M+MultiGBASE-T1/V1 transfers data and control information across the following four service interfaces:

- a) 10 Gigabit Media Independent Interface (XGMII)
- b) Technology Dependent Interface
- c) PMA service interface
- d) Medium Dependent Interface (MDI)

The XGMII is specified in Clause 46; the Technology Dependent Interface is specified in 98.4. The PMA service interface is defined in <REF> and the MDI is defined in <REF>.

#### 200.3.1 Technology Dependent Interface

*This section is only needed if Auto-Negotiation is supported*

##### 200.3.1.1 PMA\_LINK.request

##### 200.3.1.2 PMA\_LINK.indication

#### 200.3.2 PMA service interface

MultiG/100MBASE-T1/V1-L service interface is as specified in 149.2.2, with the exceptions given in this subclause.

##### 200.3.2.1 PMA\_TXMODE.indication

The transmitter in a MultiG/100MBASE-T1/V1-L link normally sends over the MDI symbols that represent an XGMII data stream with framing, scrambling and encoding of data, control information, or idles.

##### 200.3.2.2 PMA\_CONFIG.indication

As specified for MultiGBASE-T1 PHYs in 149.2.2.2.

##### 200.3.2.3 PMA\_UNITDATA.request

PMA\_UNITDATA.request(tx\_symb)

During low data rate transmission, the PMA\_UNITDATA.request simultaneously conveys to the PMA via the parameter tx\_symb the value of the symbols to be sent over the MDI. The tx\_symb may take on one of the following values:

- The DME in normal operation.
- 0 when zeros are to be transmitted in the following two cases:

when PMA\_TXMODE.indication is SEND\_Z during PMA training, and

after data mode is reached, the transmit function is in the LPI transmit mode, and lpi\_tx\_mode is QUIET.

#### 200.3.2.4 PMA\_UNITDATA.indication

The low data rate PMA generates PMA\_UNITDATA.indication(rx\_symb) messages synchronously for every symbol received at the MDI. The nominal rate of the low data rate PMA\_UNITDATA.indication primitive is  $S_{up} \times 11250$  MHz; as governed by the recovered clock.

#### 200.3.2.5 PMA\_SCRSTATUS.request

As specified for MultiGBASE-T1 PHYs in 149.2.2.5.

#### 200.3.2.6 PMA\_PCSSTATUS.request

As specified for MultiGBASE-T1 PHYs in 149.2.2.6.

#### 200.3.2.7 PMA\_RXSTATUS.indication

As specified for MultiGBASE-T1 PHYs in 149.2.2.7.

#### 200.3.2.8 PMA\_REMRXSTATUS.request

As specified for MultiGBASE-T1 PHYs in 149.2.2.8.

#### 200.3.2.9 PMA\_PCSDATAMODE.indication

As specified for MultiGBASE-T1 PHYs in 149.2.2.9.

#### 200.3.2.10 PMA\_PCS\_RX\_LPI\_STATUS.request

If EEE is supported.

#### 200.3.2.11 PMA\_PCS\_TX\_LPI\_STATUS.request

If EEE is supported.

#### 200.3.2.12 PMA\_ALERTDETECT.indication

If EEE is supported.

### 200.4 Physical Coding Sublayer (PCS) functions, MultiG+100MBASE-T1/V1

The PCS functions for MultiG/100MBASE-T1/V1-H are as specified for MultiGBASE-T1 PHYs in 149.3.

#### 200.4.1 PCS service interface (XGMII)

#### 200.4.2 PCS functions

##### 200.4.2.1 PCS Reset function

As specified for MultiGBASE-T1 PHYs in 149.3.2.1.

##### 200.4.2.2 PCS Transmit function

Example of how to reference a requirement from a previous project: The PCS transmit function in high speed direction is as specified for MultiGBASE-T1 PHYs in 149.3.2.2.

##### 200.4.2.2.1 Use of blocks

As specified for MultiGBASE-T1 PHYs in 149.3.2.2.1.

##### 200.4.2.2.2 65B RS-FEC<sup>TBD</sup> transmission code

As specified for MultiGBASE-T1 PHYs in 149.3.2.2.2.

200.4.2.2.3 Notation conventions

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.3.](#)

200.4.2.2.4 Block structure

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.4.](#)

200.4.2.2.5 Control codes

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.5.](#)

200.4.2.2.6 Ordered sets

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.6.](#)

200.4.2.2.7 Idle (/I/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.7.](#)

200.4.2.2.8 LPI (/LI/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.8.](#)

200.4.2.2.9 Start (/S/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.9](#)

200.4.2.2.10 Terminate (/T/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.10.](#)

200.4.2.2.11 Ordered set (/O/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.11.](#)

200.4.2.2.12 Error (/E/)

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.12.](#)

200.4.2.2.13 Transmit process

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.13.](#)

200.4.2.2.14 RS-FEC framing and RS-FEC encoder

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.14.](#)

200.4.2.2.15 Reed-Solomon encoder

[As specified for MultiGBASE-T1 PHYs in 149.3.2.2.17](#)

200.4.2.2.16 PCS scrambler

[The PCS Transmit function employs side-stream scrambling as defined in 149.3.4.](#)

[For 10Gb/s with PAM4 encoding the PCS scrambler is as specified for MultiGBASE-T1 PHYs in 149.3.2.2.18.](#)

[For 2.5Gb/s and 5Gb/s with PAM2 encoding, the bits of the interleaved RS-FEC superframe are scrambled using an additive scrambler. The scrambling sequence  \$DS\_n\[0\]\$  is equal to  \$Scr\_n\[0\]\$  defined in 149.3.4. The  \$DS\_n\[0\]\$  is applied as additive scrambler sequence to incoming data bits  \$D\_n\$  to generate a single scrambled data  \$A\_n\$  as shown in Equation \(149-4\).](#)

#### 200.4.2.2.17 TBD PAM encoding

The 10G PCS transmit process shall encode each output symbol to one of four PAM4 levels as specified in this subclause.

- 0 maps to  $-1$ ,
- 1 maps to  $-1/3$ ,
- 2 maps to  $+1/3$ , and
- 3 maps to  $+1$ .

~~The 5G PCS transmit process shall encode each output symbol to one of TBD PAM levels as specified in this subclause.~~

The 2.5G and 5G PCS transmit process shall encode each output symbol to one of two PAM2 levels as specified in this subclause.

- 0 maps to  $-1$ , and
- 1 maps to  $+1$ .

#### 200.4.2.2.18 EEE capability

Only need if supporting EEE

##### 200.4.2.3 PCS Receive function

[As specified for MultiGBASE-T1 PHYs in 149.3.2.3.](#)

##### 200.4.2.3.1 Frame and block synchronization

[As specified for MultiGBASE-T1 PHYs in 149.3.2.3.1. with the exception that 2.5Gb/s and 5Gb/s uses PAM2 instead of PAM4 in data mode.](#)

##### 200.4.2.3.2 PCS descrambler

[As specified for MultiGBASE-T1 PHYs in 149.3.2.3.2.](#)

##### 200.4.2.3.3 Invalid blocks

[As specified for MultiGBASE-T1 PHYs in 149.3.2.3.3.](#)

##### 200.4.3 Test-pattern generators

[As specified for MultiGBASE-T1 PHYs in 149.3.3.](#)

##### 200.4.4 Side-stream scrambler polynomials

[As specified for MultiGBASE-T1 PHYs in 149.3.4.](#)

##### 200.4.5 PMA training frame

This may be able to be a PAM2 signal that is the same for both low speed and high speed. If it is, this subclause would refer to 2xx.4.5.

##### 200.4.5.1 Generation of symbol $T_n$

[As specified for MultiGBASE-T1 PHYs in 149.3.5.1.](#)

200.4.5.2 PMA training mode descrambler polynomials

[As specified for MultiGBASE-T1 PHYs in 149.3.5.2.](#)

200.4.6 LPI signaling

Only need if supporting EEE

200.4.7 Detailed functions and state diagrams

[As specified for MultiGBASE-T1 PHYs in 149.3.7.](#)

200.4.7.1 State diagram parameters

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.](#)

200.4.7.1.1 Constants

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.1.](#)

200.4.7.1.2 Variables

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.2.](#)

200.4.8 PCS management

[As specified for MultiGBASE-T1 PHYs in 149.3.8.](#)

200.4.9 MultiG+100MBASE-T1/V1 operations, administration, and maintenance (OAM)

[As specified for MultiGBASE-T1 PHYs in 149.3.9.](#)

~~Only if OAM is used in high-speed direction.~~

200.5 Physical Coding Sublayer (PCS) functions, 100M+MultiGBASE-T1/V1

200.5.1 PCS service interface (XGMII)

The low data rate PCS service interface allows the 100M+MultiGBASE-T1/V1 PCS to transfer information to and from a PCS client. The PCS service interface is precisely defined as the 10 Gigabit Media Independent Interface (XGMII) in Clause 46.

200.5.2 PCS functions

~~NOTE: Copy of Figure 149-4 needs to be updated to reflect MII instead of XGMII.~~

200.5.2.1 PCS Reset function

The low data rate PCS reset function shall be as specified in Clause 149.3.2.1

200.5.2.2 PCS Transmit function

The PCS transmit functions for 100M+MultiGBASE-T1/V1 for the low data rate direction is described in this sub-clause.

After mapping the 8-XGMII transfers to 64B/65B blocks, the subsequent functions of the PCS Transmit process take 4 65B blocks and append 16-bit OAM/Reserved field to each group. This forms the input to the RS-FEC which adds 24 parity bits. The resulting 300 bits are then scrambled.

These bits are then mapped, to DME symbols. Transmit data-units are sent to the PMA service interface via the PMA\_UNITDATA.request primitive. In each symbol period, when communicating with the PMA,

the PCS Transmit generates a DME symbol that is transferred to the PMA via the PMA\_UNITDATA.request primitive. The symbol period,  $T$ , is  $1000 / (11.250 \times S_{up})$  ps. See Table 200–1 for the definition of  $S_{up}$ .

The operation of the PCS Transmit function is controlled by the PMA\_TXMODE.indication message received from the PMA PHY Control function. If a PMA\_TXMODE.indication message has the value SEND\_Z, PCS Transmit shall pass a vector of zeros at each symbol period to the PMA via the PMA\_UNITDATA.request primitive.

If a PMA\_TXMODE.indication message has the value SEND\_T, PCS Transmit shall generate a sequence ( $T_n$ ) defined in 149.3.5.1 to the PMA via the PMA\_UNITDATA.request primitive. These code-groups are used for training mode and only transmit the values #TBD\_training.

During training mode an Infocfield is transmitted at regular intervals containing messages for startup operation. By this mechanism, a PHY indicates the status of its own receiver to the link partner and makes requests for remote transmitter settings. (See 149.4.2.4.)

If a PMA\_TXMODE.indication message has the value SEND\_N, the PCS is in the normal mode of operation and the PCS Transmit function shall use a 65B coding technique to generate, at each symbol period, code-groups that represent data or control. During transmission, the 4 blocks of 64B encoded bits are appended with 16-bit OAM/Reserved field to form the RS-FEC input frame.

During data encoding, PCS Transmit utilizes Reed-Solomon encoders to generate and append 24 parity check bits to form 300 bit RS(50, 46, 6) RS-FEC frames.

Each RS-FEC input frame consists of 276 bits, or 46 Reed-Solomon message symbols. After encoding, the RS-FEC frames from each encoder are recombined into one single interleaved RS-FEC frame, which consists of 50 symbols, or 300 bits. The bits of the RS-FEC frame are then scrambled by the PCS using an additive scrambler, encoded in DME symbols, and transferred to the PMA.

A block diagram of the PCS Transmit functions is shown in Figure 200–5.

#### 200.5.2.2.1 Use of blocks

The PCS maps XGMII signals into 65-bit blocks inserted into an RS-FEC frame, and vice versa, using a 65B RS-FEC coding scheme. The PMA training frame synchronization allows establishment of RS-FEC frame and 65B boundaries by the PCS Synchronization process. Blocks and frames are unobservable and have no meaning outside the PCS.

#### 200.5.2.2.2 65B RS-FEC transmission code

The low speed direction RS-FEC is RS(50,46,6).

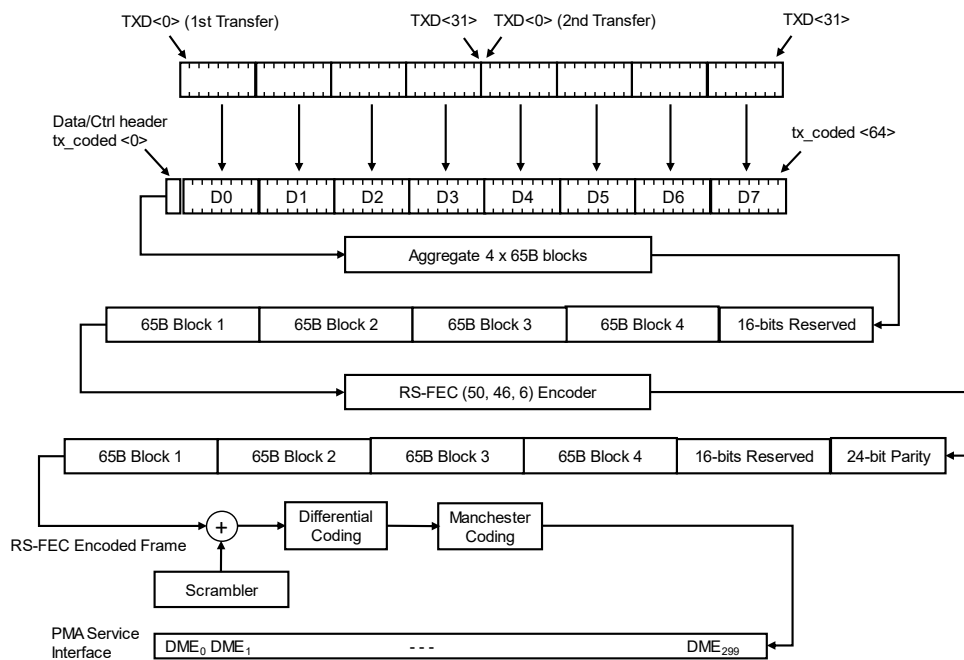


Figure 200-5 – PCS Transmit bit ordering

#### 200.5.2.2.3 Notation conventions

For values shown as binary, the leftmost bit is the first transmitted bit.

64B/65B encodes 8 data octets or control characters into a block. Blocks containing control characters also contain a block type field. Data octets are labeled  $D_0$  to  $D_7$ . Control characters other than /O/, /S/, and /T/ are labeled  $C_0$  to  $C_7$ . The control character for ordered set is labeled as  $O_0$  or  $O_4$  since it is only valid on the first octet of the XGMII. The control character for start is labeled as  $S_0$  or  $S_4$  for the same reason. The control character for terminate is labeled as  $T_0$  to  $T_7$ .

For 100M+MultiGBASE-T1/V1, two XGMII transfers provide eight characters that are encoded into one 65-bit transmission block. The subscript in the above labels indicates the position of the character in the eight characters from the XGMII transfer(s).

#### 200.5.2.2.4 Block structure

The low data rate block structure shall be as specified in Clause 149.3.2.2.4

#### 200.5.2.2.5 Control codes

The low data rate control codes shall be as specified in Clause 149.3.2.2.5

#### 200.5.2.2.6 Ordered sets

The low data rate ordered sets shall be as specified in Clause 149.3.2.2.6

#### 200.5.2.2.7 Idle (/I/)

The low data idle shall be as specified in Clause 149.3.2.2.7

#### 200.5.2.2.8 LPI (/LI/)

The low data rate LPI shall be as specified in Clause 149.3.2.2.8

#### 200.5.2.2.9 Start (/S/)

The low data rate start shall be as specified in Clause 149.3.2.2.9

#### 200.5.2.2.10 Terminate (/T/)

The low data rate terminate shall be as specified in Clause 149.3.2.2.10

#### 200.5.2.2.11 Ordered set (/O/)

The low data rate ordered set shall be as specified in Clause 149.3.2.2.11

#### 200.5.2.2.12 Error (/E/)

The low data rate error shall be as specified in Clause 149.3.2.2.12

#### 200.5.2.2.13 Transmit process

The transmit process generates blocks based upon the TXD and TXC signals received from the XGMII. 8 XGMII data transfers are encoded into an RS-FEC frame. It takes 300 PMA\_UNITDATA transfers to send an RS-FEC frame of data. Therefore, for 100MBASE-T1/V1, if the PCS is connected to an XGMII and PMA sublayer where the ratio of their transfer rates is exactly 2:75, then the transmit process does not need to perform rate adaptation. Where the XGMII and PMA sublayer data rates are not synchronized to that ratio, the transmit process needs to insert idles, delete idles, or delete sequence ordered sets to adapt between the rates.

The transmit process generates blocks as specified in the PCS 64B/65B Transmit state diagram (see Figure 200 and Figure 200). The contents of each block are contained in a vector `tx_coded<64:0>`, which is passed to the transcoder and scrambler. `tx_coded<0>` contains the data/ctrl header and the remainder of the bits contain the block payload.

#### 200.5.2.2.14 RS-FEC framing and RS-FEC encoder

The PCS uses a transmission code to improve the transmission characteristics of information to be transferred across the link and to support transmission of control and data characters.

The relationship of block bit positions to XGMII, PMA, and other PCS constructs is illustrated in Figure 200–6 for transmit and Figure 200–7 for receive. These figures illustrate the processing of a multiplicity of blocks containing 32 data octets. See 200.4.2.2.4 for information on how blocks containing control characters are mapped.

#### 200.5.2.2.15 Reed-Solomon encoder

The group of 300 bits are encoded using a Reed-Solomon encoder operating over the Galois Field  $GF(2^6)$  where the symbol size is 6 bits. The encoder processes 46 6-bit RS-FEC message symbols to generate 4 6-bit RS-FEC parity symbols, which are then appended to the message to produce a codeword of 50 6-bit

RS-FEC symbols. For the purposes of this clause, the particular Reed-Solomon code is denoted as RS-FEC(50,46,6).

#### 200.5.2.2.16 PCS scrambler

The bits of the interleaved RS-FEC superframe are scrambled using an additive scrambler. For each bit,  $D_n$ , a scrambler bit is generated from the side-stream scrambler. The scrambler bit,  $DS_n$ , is equal to  $Scrn[0]$  defined in 149.3.4.

$DS_n$  is applied as additive scrambler sequences to incoming data bits  $D_n$  to generate the scrambled data bit  $A_n$  as shown in Equation (200–4).

$$A_n = DS_n \oplus D_n \quad (200-4)$$

#### 200.5.2.2.17 Differential Manchester encoding (DME)

The scrambled data bit,  $A_n$ , is encoded using Differential Manchester Encoding (DME).

#### 200.5.2.2.18 EEE capability

*Only need if supporting EEE*

#### 200.5.2.3 PCS Receive function

The PCS Receive function shall conform to the PCS 64B/65B Receive state diagram in Figure <REF> and Figure <REF>, and the PCS Receive bit ordering in Figure <REF> including compliance with the associated state variables as specified in <REF>.

The PCS Receive function accepts received code-groups provided by the PMA Receive function via the parameter  $rx\_symb$ . The PCS receiver uses knowledge of the encoding rules and PMA training alignment to correctly align the 65B RS-FEC frames. The received DME symbols are demapped and descrambling is performed.

Following descrambling, the L-interleaved RS-FEC superframe is de-interleaved and the Reed-Solomon frames are decoded with Reed-Solomon error correction. Frames that cannot be corrected are marked with error symbols by the decoder. The RS-FEC decoded frame is then separated into a 16-bit OAM/Reserved field and 4 64B/65B blocks. This process generates the 64B/65B block vector  $rx\_coded<64:0>$ , which is then decoded to form the XGMII signals  $RXD<31:0>$  and  $RXC<3:0>$  as specified in the PCS 64B/65B Receive state diagram (see Figure <ref> and Figure <ref>). Two XGMII data transfers are decoded from each block. Where the XGMII and PMA sublayer data rates are not synchronized, the receive process inserts idles, deletes idles, or deletes sequence ordered sets to adapt between rates.

During PMA training mode, PCS Receive checks the received TBD framing and signals the reliable acquisition of the descrambler state by setting the  $scr\_status$  parameter of the  $PMA\_SCRSTATUS.request$  primitive to OK.

When the PCS Synchronization process has obtained synchronization, the RS-FEC frame error ratio (RFER) monitor process monitors the signal quality and asserts  $hi\_rfer$  to indicate excessive RS-FEC frame errors. If 40 consecutive RS-FEC frame errors are detected, the  $block\_lock$  flag is de-asserted. The  $block\_lock$  flag is re-asserted upon detection of a valid RS-FEC frame. When  $block\_lock$  is asserted and  $hi\_rfer$  is de-asserted, the PCS Receive process continuously accepts blocks. The PCS Receive process monitors these blocks and generates  $RXD<31:0>$  and  $RXC<3:0>$  on the XGMII.

When the receive channel is in training mode, the PCS Synchronization process continuously monitors PMA\_RXSTATUS.indication(loc\_rcvr\_status). When loc\_rcvr\_status indicates OK, then the PCS Synchronization process accepts data-units via the PMA\_UNITDATA.indication primitive. It attains frame and block synchronization based on the PMA training frames and conveys received blocks to the PCS Receive process. The PCS Synchronization process sets the block\_lock flag to indicate whether the PCS has obtained synchronization. The PMA training frame includes an alignment bit every TBD symbols, which is aligned with the PCS partial PHY frame boundary, as well as an Infield, which is inserted in the 16th PCS partial PHY frame. When the PCS Synchronization process is synchronized to this pattern, block\_lock is asserted.

#### 200.5.2.3.1 Frame and block synchronization

When operating in the data mode, the receiving PCS shall form a DME stream from the PMA\_UNITDATA.indication primitive by concatenating requests in order from rx\_DME\_0 to rx\_DME\_299 (see Figure <REF>). It obtains block lock to the PHY frames during training using synchronization bits provided in the training frames.

#### 200.5.2.3.2 PCS descrambler

The descrambler processes the payload to reverse the effect of the scrambler using the same polynomial. The PCS descrambles the data stream and returns the proper sequence of symbols to the decoding process for generation of RXD<31:0> to the XGMII. For side-stream descrambling, the MASTER PHY shall employ the receiver descrambler generator polynomial per Equation (149–6) and the SLAVE PHY shall employ the receiver descrambler generator polynomial per Equation (149–5).

#### 200.5.2.3.3 Invalid blocks

A block is invalid if any of the following conditions exist:

- a) The block type field contains a reserved value.
- b) Any control character contains a value not in Table <REF>.
- c) Any O code contains a value not in Table <REF>.
- d) The block contains information from the payload of an invalid RS-FEC frame.

The PCS Receive function shall check the integrity of the RS-FEC parity bits defined in <REF>. If the check fails the RS-FEC frame is invalid.

The R\_BLOCK\_TYPE of an invalid block is set to E.

#### 200.5.3 Test-pattern generators

For 100M+MultiGBASE-T1/V1 test-pattern generator follows Clause 149.3.3, with the exception that the transmission follows illustration in Figure <REF> instead of Figure 149-6 and Figure <REF> instead of Figure 149-7.

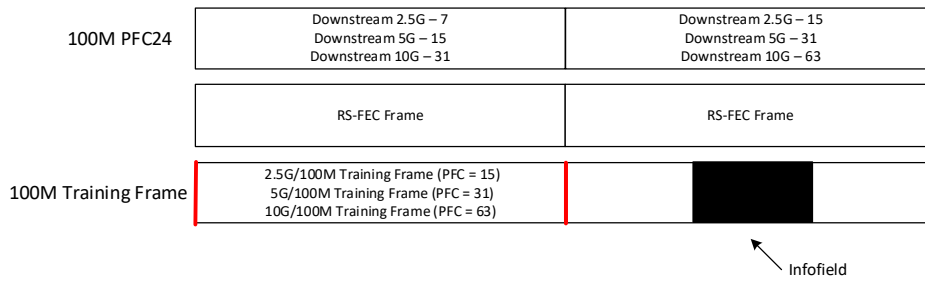
#### 200.5.4 Side-stream scrambler polynomials

For 100M+MultiGBASE-T1/V1 side-stream scrambler is as specified in 149.3.4.

### 200.5.5 PMA training frame

During PMA training, the training frames are embedded with indicators to establish alignment to the RS-FEC. Each training frame is composed of 2 partial PHY frames. Each partial PHY frame has the same duration as one RS\_FEC frame. The second partial PHY frame is embedded with an information field used to exchange messages between link partners. The timing relationship among training frame, partial frame, RS-FEC frame, and partial PHY frame count (PFC24) are shown in Figure 200.

**Figure XXX—Timing relationship to PFC24**



PMA training frame encoding is based on the generation, at time  $n$ , of the bit  $S_n$ . The first bit is inverted in each partial PHY frame. The 100<sup>th</sup> bit to the 195<sup>th</sup> bit (counting from 0) of the second partial PHY frame are XORed with the contents of the Infofield. Each partial PHY frame is 300 bits long, beginning at  $S_n$  where  $(n \bmod 300) = 0$ . See Equation (200).

$$S_n = \begin{cases} Scr_n[0] \oplus InfoField_{(n \bmod 100)} & 400 \leq (n \bmod 600) \leq 495 \\ Scr_n[0] \oplus 1 & \text{else if } (n \bmod 300) = 0 \\ Scr_n[0] & \text{otherwise} \end{cases}$$

One 100M training frame has the same duration as 1, 2, and 4 downstream training frames for 2.5G, 5G, and 10G respectively. To keep the PFC24 update rate in sync with between the upstream and downstream training frames, the value in the PFC24 field shall be  $(m+1)*2q - 1$  where  $m$  is the  $m^{\text{th}}$  training frame and  $q$  is 8, 16, or 32 when the downstream is 2.5G, 5G, and 10G respectively. Each partial frame increments at a rate of  $q$ , with the PFC of  $(m+1)*2q - 1 - q$  for the first partial frame of the training frame and  $(m+1)*2q - 1$  for the second partial frame.

200.5.5.1 Generation of symbol  $T_n$

The 100M+MultiGBASE-T1/V1  $T_n$  symbol is TBD.

200.5.5.2 PMA training mode descrambler polynomials

The 100M+MultiGBASE-T1/V1 training mode descrambler is TBD.

200.5.6 LPI signaling

Only need if supporting EEE

200.5.7 Detailed functions and state diagrams

[As specified for MultiGBASE-T1 PHYs in 149.3.7.](#)

200.5.7.1 State diagram parameters

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.](#)

200.5.7.1.1 Constants

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.1.](#)

200.5.7.1.2 Variables

[As specified for MultiGBASE-T1 PHYs in 149.3.7.1.2.](#)

200.5.8 PCS management

[As specified for MultiGBASE-T1 PHYs in 149.3.8.](#)

200.5.9 100M+MultiGBASE-T1/V1 operations, administration, and maintenance (OAM)

Only if OAM is used in low speed direction.

200.6 Physical Medium Attachment (PMA) sublayer, MultiG+100MBASE-T1/V1

~~I did not include all subclauses as they can vary with implementation. You can look at any PHY project that is similar to see which may be needed. Other subclauses may be added as baselines are chosen.~~

The high speed PMA functions are as specified in 149.4, with the following exception:-

1) [The 2.5Gb/s signaling uses PAM2 instead of PAM4.](#)

~~2)~~ [The 5Gb/s signaling uses PAM2 instead of PAM4.\)](#)

200.7 Physical Medium Attachment (PMA) sublayer, 100M+MultiGBASE-T1/V1

~~I did not include all subclauses as they can vary with implementation. You can look at any PHY project that is similar to see which may be needed. Other subclauses may be added as baselines are chosen.~~

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The low speed PMA Transmit function comprises a transmitter to generate a DME signal on the MDI interface.

#### 200.7.1 PMA functional specifications

##### 200.7.2 PMA functions

The PMA sublayer comprises one PMA Reset function and five simultaneous and asynchronous operating functions. The PMA operating functions are PHY Control, PMA Transmit, PMA Receive, Link Monitor, and Clock Recovery. All operating functions are started immediately after the successful completion of the PMA Reset function.

The PMA reference diagram, Figure <REF>, shows how the operating functions relate to the messages of the PMA service interface and the signals of the MDI. Connections from the management interface, comprising the signals MDC and MDIO, to other layers are pervasive and are not shown in Figure <REF>.

##### 200.7.2.1 PMA Reset function

The PMA Reset function shall be executed whenever one of the two following conditions occur:

- a) Power for the device containing the PMA has not reached the operating state.
- b) The receipt of a request for reset from the management entity.

PMA Reset sets pma\_reset = ON while any of the above reset conditions hold TRUE. All state diagrams take the open-ended pma\_reset branch upon execution of PMA Reset. The reference diagrams do not explicitly show the PMA Reset function.

The MultiG/100MBASE-T1/V1-L PMA takes no longer than TBD ms to enter the PCS\_DATA state after exiting from reset or low power mode (see Figure 149–32).

##### 200.7.2.2 PMA Transmit

The PMA Transmit function comprises a transmitter to generate a DME modulated signal on the single balanced pair of conductors (T1) or Coaxial cable (V1). When the PHY Control state diagram (Figure 149–32) is not in the DISABLE\_TRANSMITTER state, PMA Transmit shall continuously transmit pulses modulated by the symbols given by tx\_symb onto the MDI. During Link Synchronization, when sync\_link\_control = DISABLE and Auto-Negotiation is either not enabled or is not implemented, the sync\_tx\_symb output by the PHY Link Synchronization function shall be used in place of tx\_symb as the data source for PMA Transmit. The signals generated by PMA Transmit shall comply with the electrical specifications given in 149.5.2.

When the PMA\_CONFIG.indication parameter config is MASTER, the PMA Transmit function shall source TX\_TCLK from a local clock source while meeting the transmit jitter requirements of 149.5.2.3. The MASTER-SLAVE relationship shall include loop timing. If the PMA\_CONFIG.indication parameter config is SLAVE, the PMA Transmit function shall source TX\_TCLK from the recovered clock of 149.4.2.8 while meeting the jitter requirements of TBD.

The PMA Transmit fault function is optional. The faults detected by this function are implementation specific. If the MDIO interface is implemented, then this function shall be mapped to the transmit fault bit as specified in 45.2.1.7.4.

When the PMA\_transmit\_disable variable is set to TRUE, this function shall turn off the transmitter so that the average launch power of the transmitter is less than –53 dBm.

#### 200.7.2.3 PMA Receive function

The low speed PMA Receive function comprises a receiver for DME signal on the MDI. PMA Receive contains the circuits necessary to both detect symbol sequences from the signals received at the MDI and to present these sequences to the PCS Receive function. The PMA translates the signals received at the MDI into the PMA\_UNITDATA.indication parameter rx\_symb. The quality of these symbols shall allow RFER of less than 2 x after RS-FEC decoding, over a channel meeting the requirements of 149.7.

The low speed direction PMA Receiver function uses the parameters pcs\_status and scr\_status, along with other applicable receiver status, and generates the loc\_rcvr\_status variable accordingly. The loc\_rcvr\_status variable is expected to become NOT\_OK when the link partner's tx\_mode changes to SEND\_Z from any other value (see the PHY Control state diagram in Figure 149–32). The precise algorithm for generation of loc\_rcvr\_status is implementation dependent.

The receiver uses the sequence of symbols during the training sequence to detect and correct for pair polarity swaps.

The PMA Receive fault function is optional. The PMA Receive fault function is the logical OR of the link\_status = FAIL and any implementation specific fault. If the MDIO interface is implemented, then this function shall contribute to the receive fault bit specified in 45.2.1.7.5 and 45.2.1.193.7.

#### 200.7.2.4 PHY Control function

The 100M+MultiGBASE-T1/V1 PHY control functions are as specified in 149.4.2.4.

#### 200.7.2.5 Link Monitor function

The 100M+MultiGBASE-T1/V1 link monitoring functions are as specified in 149.4.2.5.

#### 200.7.2.6 PHY Link Synchronization

The 100M+MultiGBASE-T1/V1 link synchronization is TBD.

#### 200.7.2.7 Refresh monitor function

*Only needed if EEE is implemented.*

#### 200.7.2.8 Clock Recovery function

The Clock Recovery function shall provide a clock suitable for signal sampling so that the RFER indicated in 200.7.2.4 is achieved. The received clock signal is expected to be stable and ready for use when training has been completed. The received clock signal is supplied to the PMA Transmit function by received\_clock.

### 200.7.3 MDI, T1

*The MDI signals are as specified in 149.4.3, with the following exceptions:*

- 1) The 100Mb/s exception that low speed signaling uses DME instead of PAM4.
- 2) The 2.5Gb/s signaling uses PAM2 instead of PAM4.
- 3) The 5Gb/s signaling uses PAM2 instead of PAM4.

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#### 200.7.4 MDI, V1

The MDI signals are as specified in 149.4.3, with the following exceptions:

- 1) ~~The exception that low speed signaling uses DME instead of PAM4, and that the~~ signals are single ended instead of differential.
- 2) The 100Mb/s signaling uses DME instead of PAM4.
- 3) The 2.5Gb/s signaling uses PAM2 instead of PAM4.
- 4) The 5Gb/s signaling uses PAM2 instead of PAM4.

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#### 200.7.5 State variables

The 100M+MultiGBASE-T1/V1 state variables are as specified in 149.4.4.

#### 200.7.6 State diagrams

The 100M+MultiGBASE-T1/V1 state diagrams are as specified in 149.4.4.

#### 200.8 Physical Medium Dependent (PMD) sublayer, T1

This subclause defines the electrical characteristics of the PMD and specifies PMD-to-MDI interface tests, for differential balanced pair (T1).

##### 200.8.1 Test modes

The MultiG+100M/100M+MultiGBASE-T1 test modes, including the test fixtures, are as specified in 149.5.1.

*Editorial Note: The test mode transmit signals may belong in the PMA Clauses (200.6 and 200.7)*

##### 200.8.2 Transmitter electrical specifications

The MultiG+100M/100M+MultiGBASE-T1 transmitter electrical specifications are as specified in 149.5.2, with the exceptions listed in this sub-clause.

###### 200.8.2.1 Maximum output droop

As specified for MultiGBASE-T1 PHYs in 149.5.2.1.

###### 200.8.2.2 Transmitter linearity

As specified for MultiGBASE-T1 PHYs in 149.5.2.2.

###### 200.8.2.3 Transmitter timing jitter

As specified for MultiGBASE-T1 PHYs in 149.5.2.3.

###### 200.8.2.4 Transmitter power spectral density (PSD) and power level

The MultiG+100M+MultiGBASE-T1 transmitter power spectral density (PSD) and power level are as specified in 149.5.2.4.

The 100M+MultiGBASE-T1 transmitter power spectral density (PSD) when measured using test mode 3 and the test fixture shown in Figure 147–16, or equivalent, the transmitter Power Spectral Density (PSD) shall be between the upper and lower masks specified in Equation (200.8–1) and Equation (200.8–2).

$$\text{UpperPSD}(f) = \begin{cases} -78 & 3 \leq f < 150 \\ -57 - 0.14f & 150 \leq f < 250 \\ -92 & 250 \leq f < 400 \end{cases} \text{dBm/Hz} \quad (200.8-1)$$

and

$$\text{LowerPSD}(f) = \begin{cases} -104 + 0.2f & 50 \leq f < 100 \\ -64 - 0.2f & 100 \leq f < 150 \end{cases} \text{dBm/Hz} \quad (200.8-2)$$

where  $f$  is the frequency in MHz.

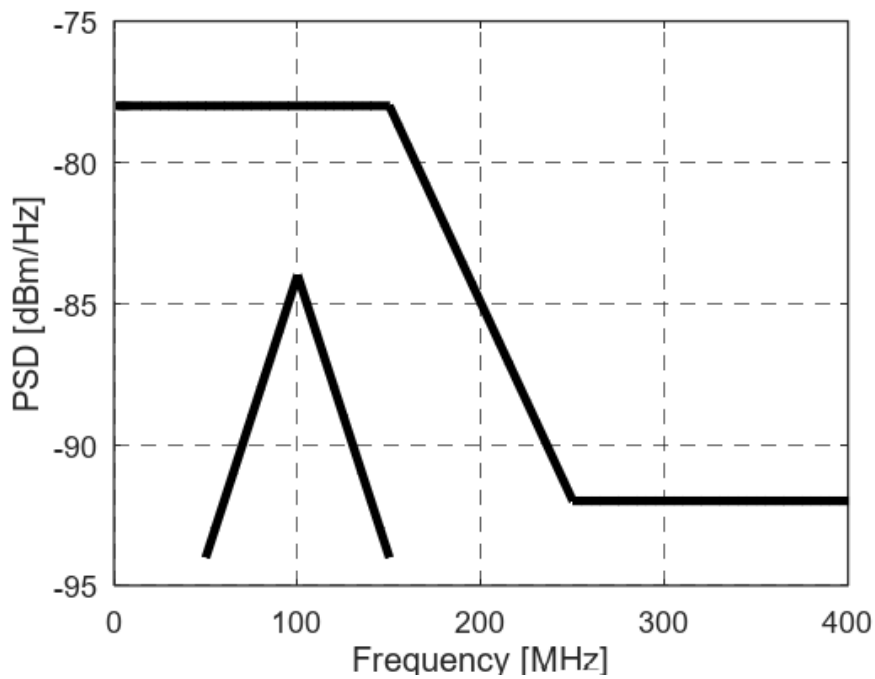


Figure 200.9-1—PSD masks for low speed as specified by Equations (200.8-1) and (200.8-2)

#### 200.8.2.5 Transmitter peak differential output

As specified for MultiGBASE-T1 PHYs in 149.5.2.5.

#### 200.8.2.6 Transmitter clock frequency

As specified for MultiGBASE-T1 PHYs in 149.5.2.6.

#### 200.8.3 Receiver electrical specifications

The MultiG+100M/100M+MultiGBASE-T1 Receiver electrical specifications are as specified in 149.5.3, with the exception listed in this sub-clause.

The cabling used is according to Clause 200.11, instead of Clause 149.7.

#### 200.8.3.1 Receiver differential input signals

Differential signals received at the MDI that were transmitted from a remote transmitter within the specifications of 200.8.2 and have passed through a link specified in 200.11 shall be received with a BER less than  $10^{-12}$  after RS-FEC decoding, and sent to the XGMII after link reset completion. This specification can be verified by a frame error ratio less than  $7.8 \times 10^{-9}$  for 800 octet frames with minimum IPG or greater than 220-octet IPG.

#### 200.8.3.2 External noise rejection

As specified for MultiGBASE-T1 PHYs in 149.5.3.2.

#### 200.8.4 MDI

Communication through the MDI is summarized in 149.4.3.1 and 149.4.3.2, with the exceptions listed in 200.7.3 for T1 links.

##### ~~200.8.4.1 MDI signals transmitted by the PHY~~

##### ~~200.8.4.3 Signals received at the MDI~~

#### 200.9 Physical Medium Dependent (PMD) sublayer, V1

This subclause defines the electrical characteristics of the PMD and specifies PMD-to-MDI interface tests, for coaxial cables (V1).

#### 200.9.1 Test modes

The test modes described in 149.5.1 shall be provided to allow for testing of the transmitter jitter, transmitter distortion, transmitter PSD, transmitter droop, and BER.

*Editorial Note: The test mode transmit signals may belong in the PMA Clauses 200.6 and 200.7*

##### 200.9.1.1 Test fixtures

The following fixtures, or their equivalents, as shown in Figure 200.9.1.1 - 1, Figure 200.9.1.1 - 2, Figure 200.9.1.1 - 3, and Figure 200.9.1.1 - 3, in stated respective tests, are defined for measuring the transmitter specifications for data communication only.

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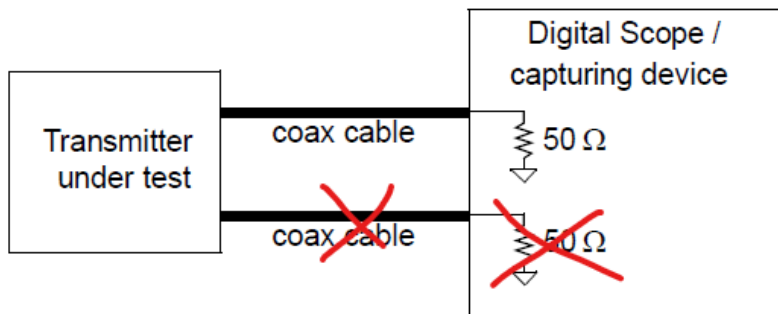


Figure 200.9.1.1—1—Transmitter test fixture 1 for transmitter droop measurement and transmitter linearity measurement

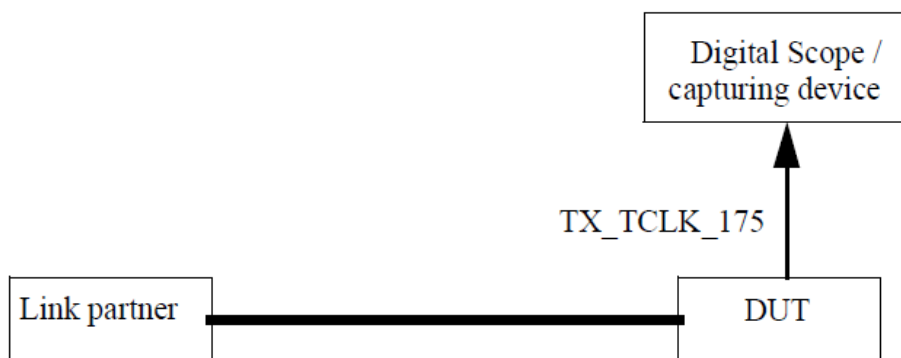


Figure 200.9.1.1—2—Transmitter test fixture 2 for MASTER and SLAVE clock jitter measurement

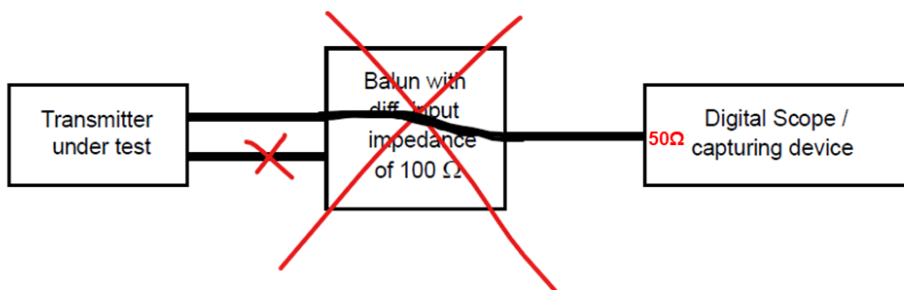
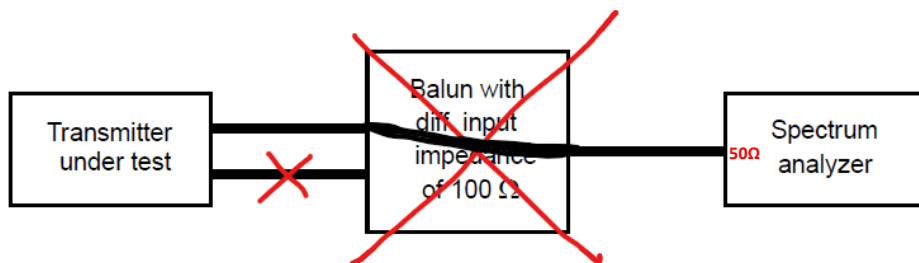


Figure 200.9.1.1—3—Transmitter test fixture 3 for MDI jitter measurement



**Figure 200.9.1.1—4—Transmitter test fixture 4 for power spectral density measurement and transmit power level measurement**

## 200.9.2 Transmitter electrical specifications

The PMA provides the Transmit function specified in 200.7.2.2 in accordance with the electrical specifications of this clause. The electrical input shall be AC-coupled, i.e., it shall present a high DC common-mode impedance at the MDI. There may be various methods for AC-coupling in actual implementations.

Where a load is not specified, the transmitter shall meet the requirements of this clause with a 50 Ohm resistive differential load connected to each transmitter output. Transmitter electrical tests are specified with a load tolerance of  $\pm 0.1\%$ .

### 200.9.2.1 Maximum output droop

With the transmitter in test mode 6 and using the transmitter test fixture 1 shown in Figure 200.9.1.1—1, the magnitude of both the positive and negative droop shall be less than 15%, measured with respect to an initial value at 4 ns after the zero crossing and a final value at 16 ns after the zero crossing (12 ns period).

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### 200.9.2.2 Transmitter linearity

With the transmitter in test mode 4 and using the transmitter test fixture 1 shown in Figure 200.9.1.1—1, the test defined in 120D.3.1.2 shall be performed. For 10Gb/s the ideal PAM4 level of 1/3 should be used for effective symbol levels of ES1 and ES2. The transmitter SNDR distortion, as specified in 120D.3.1.6, shall exceed TBD dB for 100M+MultiGBASE-V1, 38 dB for 10G+100MBASE-V1, 36 dB for 5G+100MBASE-V1, and 35 dB for 2.5G+100MBASE-V1 modes.

### 200.9.2.3 Transmitter timing jitter

The transmitter timing jitter is measured by capturing the TX\_TCLK\_175 waveform in both MASTER and SLAVE configurations while in test mode 1 using the transmitter test fixture 2 shown in Figure 200.9.1.1—2.

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The transmit timing jitter is TBD.

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200.9.2.4 Transmitter power spectral density (PSD) and power level

When measured using test mode 3 and the test fixture shown in Figure <REF>, or equivalent, the transmitter Power Spectral Density (PSD) shall be between the upper and lower masks specified in Equation (200.9-1) and Equation (200.9-2).

$$\text{UpperPSD}(f) = \begin{cases} -81 & 3 \leq f < 150 \\ -60 - 0.14f & 150 \leq f < 250 \\ -95 & 250 \leq f < 400 \end{cases} \text{dBm/Hz} \quad (200.9-1)$$

and

$$\text{LowerPSD}(f) = \begin{cases} -107 + 0.2f & 50 \leq f < 100 \\ -67 - 0.2f & 100 \leq f < 150 \end{cases} \text{dBm/Hz} \quad (200.9-2)$$

where  $f$  is the frequency in MHz.

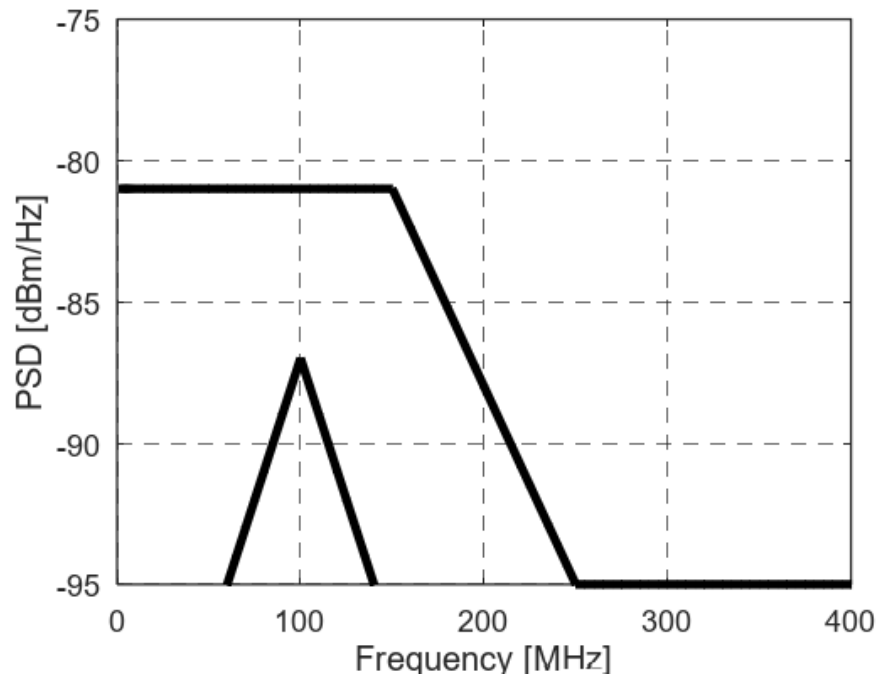


Figure 200.9-1—PSD masks for low speed as specified by Equations (200.9-1) and (200.9-2)

200.9.2.5 Transmitter peak output

When measured with 50 Ohm termination, the transmit signal at the MDI shall be less than TBD V peak. This limit applies to all transmitted symbol sequences, including SEND\_S, SEND\_T, and SEND\_N.

200.9.2.6 Transmitter clock frequency  
As specified for MultiGBASE-T1 PHYs in 149.5.2.6.

200.9.3 Receiver electrical specifications  
The PMA provides the Receive function specified in TBD in accordance with the electrical specifications of this clause using cabling that is within the limits specified in TBD.

200.9.3.1 Receiver input signals  
Differential signals received at the MDI that were transmitted from a remote transmitter within the specifications of 200.7.2 and have passed through a link specified in 200.12 shall be received with a BER less than  $10^{-12}$  after RS-FEC decoding, and sent to the XGMII after link reset completion. This specification can be verified by a frame error ratio less than  $7.8 \times 10^{-9}$  for 800 octet frames with minimum IPG or greater than 220-octet IPG.

200.9.3.2 External noise rejection  
External noise rejection is TBD.

200.9.4 MDI  
Communication through the MDI is summarized in 149.4.3.1 and 149.4.3.2, with the exceptions listed in 200.7.4 for V1 links.

~~200.9.4.1 MDI signals transmitted by the PHY~~  
~~200.9.4.3 Signals received at the MDI~~

200.10 Management interface

200.11 Link segment characteristics, T1  
2.5G+100MBASE-T1, 5G+100MBASE-T1, and 10G+100MBASE-T1 are designed to operate over a single shielded balanced pair of conductors that meet the requirements specified in this subclause. The single shielded balanced pair of conductors supports an effective data rate of 2.5 Gb/s, 5 Gb/s, and 10 Gb/s in one direction and simultaneously 100Mb/s in the other direction. The term link segment used in this clause refers to a single balanced pair of conductors (cable or backplane) operating in full duplex.

For the three different PHY types, link segment parameters are specified to different upper frequencies, given by the parameter  $F_{max}$  shown in Equation (200.11-1).

$$F_{max} = 4000 \times S \text{ (200.11-1)}$$

See Table 200-1 for the definition of  $S$ .

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#### 200.11.1 Link transmission parameters

The transmission characteristics for the MultiG+100MBASE-T1 link segment are specified to support operation over automotive temperature and electromagnetic conditions.

##### 200.11.1.1 Insertion loss

The insertion loss of each MultiG+100MBASE-T1 link segment shall meet the values determined using Equation (200.11-2).

$$\text{Insertion loss}(f) \leq \text{TBD (dB)} \quad (200.11-2)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq f_{\text{max}}$

The insertion loss is illustrated in Figure TBD.

##### 200.11.1.2 Differential characteristic impedance

The nominal differential characteristic impedance of the link segment is 100 Ohm.

##### 200.11.1.3 Return loss

The return loss of each MultiG+100MBASE-T1 link segment shall meet the values determined using Equation (200.11-2).

$$\text{Return loss}(f) > \text{TBD (dB)} \quad (200.11-3)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq f_{\text{max}}$

The return loss is illustrated in Figure TBD.

##### 200.11.1.4 Coupling attenuation

The coupling attenuation of each MultiG+100MBASE-T1 link shall be as specified in 149.7.1.4.

##### 200.11.1.5 Screening attenuation

The screening attenuation of each MultiG+100MBASE-T1 link shall be as specified in 149.7.1.5.

##### 200.11.1.6 Maximum link delay

The maximum link delay of each MultiG+100MBASE-T1 link shall be as specified in 149.7.1.6.

## 200.11.2 Coupling parameters between link segments

The coupling parameters between link segments shall be as specified in 149.7.2.

### 200.11.2.1 Power sum alien near-end crosstalk (PSANEXT)

The PSANEXT shall be as specified in 149.7.2.1.

### 200.11.2.2 Power sum alien attenuation to crosstalk ratio far-end (PSAACRF)

The PSAACRF shall be as specified in 149.7.2.2.

## 200.12 Link segment characteristics, V1

2.5G+100MBASE-V1, 5G+100MBASE-V1, and 10G+100MBASE-V1 are designed to operate over a single coaxial cable that meet the requirements specified in this subclause. The single coaxial cable supports an effective data rate of 2.5 Gb/s, 5 Gb/s, and 10 Gb/s in one direction and simultaneously 100Mb/s in the other direction. The term *link segment* used in this clause refers to a coaxial cable operating in full duplex.

For the three different PHY types, link segment parameters are specified to different upper frequencies, given by the parameter  $F_{\max}$  shown in Equation (200.11–1).

### 200.12.1 Link transmission parameters

The transmission characteristics for the MultiG+100MBASE-V1 link segment are specified to support operation over automotive temperature and electromagnetic conditions.

#### 200.12.1.1 Insertion loss

The insertion loss of each MultiG+100MBASE-V1 link segment shall meet the values determined using Equation (200.12-1).

$$\text{Insertion loss}(f) \leq \text{TBD (dB)} \quad (200.12-1)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq F_{\max}$

The insertion loss is illustrated in Figure TBD.

#### 200.12.1.2 Differential Characteristic impedance

The nominal characteristic impedance of the link segment is 50 Ohm.

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#### 200.12.1.3 Return loss

The return loss of each MultiG+100MBASE-V1 link segment shall meet the values determined using Equation (200.12-2).

$$\text{Return loss}(f) > \text{TBD (dB)} \quad (200.12-2)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq f_{\text{max}}$

The return loss is illustrated in Figure TBD.

#### 200.12.1.4 Coupling attenuation

The coupling attenuation is not defined for coaxial cables.

#### 200.12.1.5 Screening attenuation

Where coaxial cabling is used, the minimum screening attenuation for a link segment is TBD dB for all frequencies between 30 MHz and  $f_{\text{max}}$  MHz. Screening attenuation is tested as specified in IEC 62153-4-7 using triaxial tube-in-tube method. Additional screening attenuation test methodologies are defined in Annex 149A.

#### 200.12.1.6 Maximum link delay

The maximum link delay of each MultiG+100MBASE-T1 link shall be as specified in 149.7.1.6.

#### 200.12.2 Coupling parameters between link segments

I wasn't sure what the correct parameters are, so I just copied the T1 crosstalk titles for placeholders.

##### 200.12.2.1 Power sum alien near-end crosstalk (PSANEXT)

The power sum ANEXT loss between a disturbed link segment and the disturbing link segment shall meet the values determined using Equation (200.12-3).

$$\text{PSANEXT loss}(f) > \text{TBD (dB)} \quad (200.12-3)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq 4000$

The PSANEXT loss is illustrated in Figure TBD.

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#### 200.12.2.2 Power sum alien attenuation to crosstalk ratio far-end (PSAACRF)

The power sum AACRF between a disturbed link segment and the disturbing link segment shall meet the values determined using Equation (200.12-4).

$$\text{PSAACRF loss}(f) > \text{TBD (dB)} \quad (200.12-4)$$

where

$f$  is the frequency in MHz;  $1 \leq f \leq 4000$

The PSAACRF loss is illustrated in Figure TBD.

### 200.13 MDI specification, T1

#### 200.13.1 MDI connectors

The MDI connectors are as specified in 149.8.1.

#### 200.13.2 MDI electrical specification

##### 200.13.2.1 MDI return loss

The differential impedance at the MDI for each transmit/receive channel shall be such that any reflection due to signals incident upon the MDI from the cabling relative to the incident signal are per the relationship shown in Equation (200-1). For coaxial cabling a nominal characteristic impedance of 50Ω is used.

$$\text{MDI\_Return\_Loss}(f) \leq \begin{cases} 18 - 20 \log_{10} \left( \frac{f}{50} \right) & 10 \leq f < 50 \\ 18 & 50 \leq f < 400 \\ 18 - 13 \log_{10} \left( \frac{f}{400} \right) & 400 \leq f < F_{\max} \end{cases} \text{ (dB)} \quad (200-1)$$

where

$f$  is the frequency in MHz.

**NOTE:** The equation above is the agreed text, but there is an error in the sign of the second term in the frequency range from 10Mbps to 50Gbps. It should be "18+20 log10(f/50)".

For MultiG+100M/100M+MultiGBASE-T1 the maximum applicable frequency,  $F_{\max}$ , for the MDI return loss is 4000 MHz.

**Note:**  $F_{\max}$  should scale with baud rate once the transmit signals are established.

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The MDI return loss for 10G+100MBASE-T1 and 100M+10GBASE-T1 is illustrated in Figure 200-2.

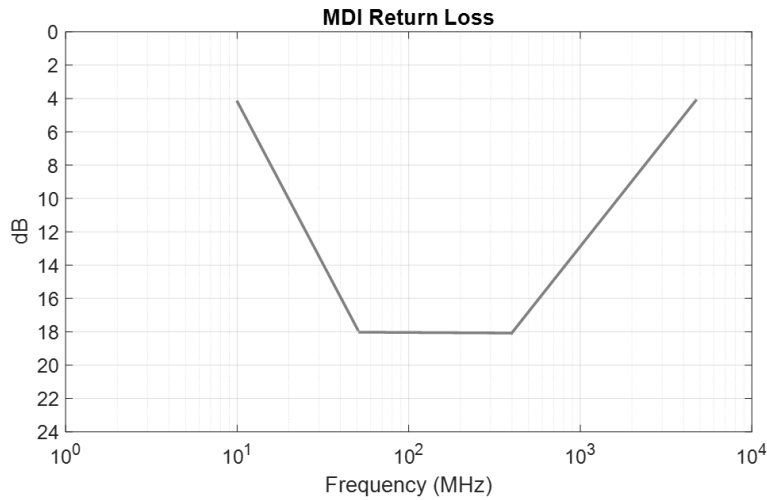


Figure 200-2—MDI return loss calculated using Equation (200-1)

200.13.3 MDI fault tolerance

The MDI fault tolerance shall comply with 96.8.3.

200.14 MDI specification, V1

200.14.1 MDI connectors

Where coax cabling is used, the mechanical interface to the coax cabling is a single pin connector with a shield. Further specification of the mechanical interface is beyond the scope of this standard.

200.14.2 MDI electrical specification

200.14.2.1 MDI return loss

The MDI return loss for coax cables is as specified in 200.13.2.1.

200.14.3 MDI fault tolerance

The MDI fault tolerance shall comply with 96.8.3.

200.15 Environmental specifications

The environmental specifications for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.9.

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200.15.1 General safety

[The general safety specifications for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.9.1.](#)

200.15.2 Network safety

[The network safety specifications for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.9.2.](#)

200.15.2.1 Environmental safety

[The environmental safety specifications for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.9.2.1.](#)

200.15.2.2 Electromagnetic compatibility

[The electromagnetic compatibility safety specifications for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.9.2.2.](#)

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200.16 Delay constraints

The delay constraints for MultiG+100M/100M+MultiGBASE-T1/V1 are as specified in 149.10 with the exceptions and extensions in this sub-clause.

The delay limits for 100Mb/s low speed direction are TBD.

200.17 Protocol implementation conformance statement (PICS) proforma for Clause 200